

Model Verification using satellite observations and object-based verification methods

Sarah M. Griffin *

Jason A. Otkin *

Christopher M. Rozoff ♦

Justin M. Sieglaff *

Lee M. Cronce *

Curtis R. Alexander ★

Tara L. Jensen ^

Jamie K. Wolff ^

* Cooperative Institute for Meteorological Satellite Studies, University of Wisconsin–Madison, Madison, WI

♦ Research Applications Laboratory, National Center for Atmospheric Research, Boulder, CO

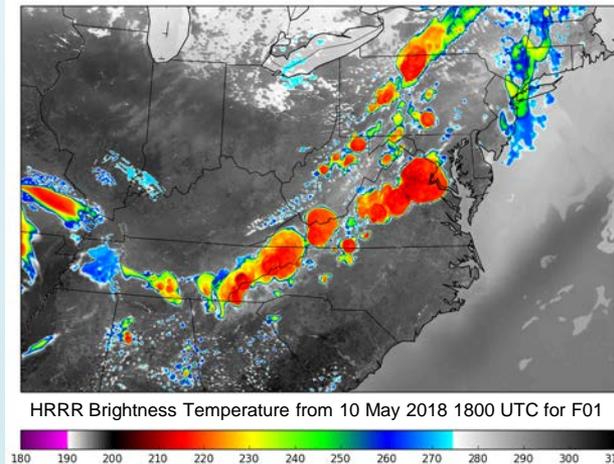
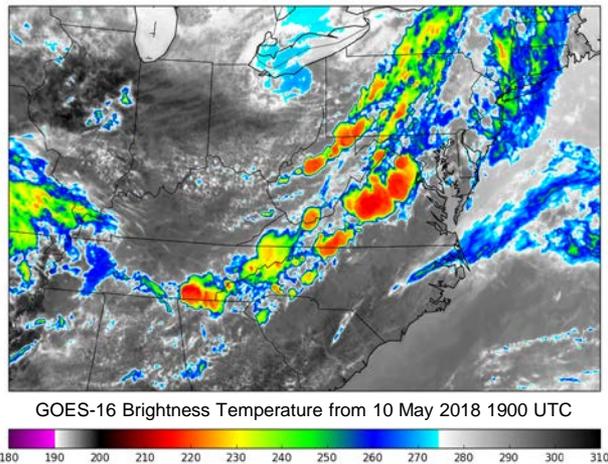
★ NOAA/Earth System Research Laboratory, Boulder, CO

^ Research Applications Laboratory, National Center for Atmospheric Research, and Developmental Testbed Center, Boulder, CO

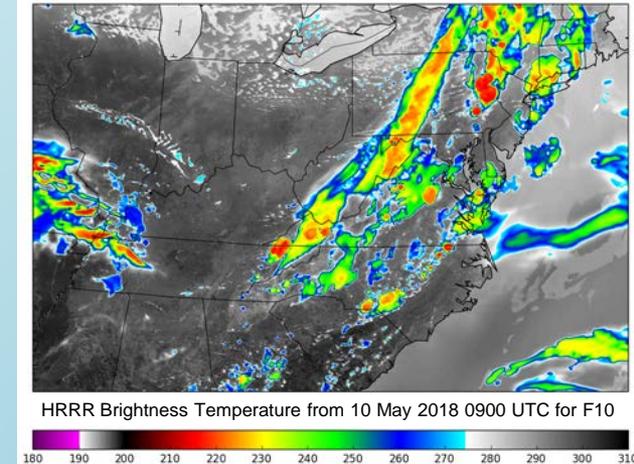
Motivation

Many traditional metrics for assessing forecast accuracy are point-based metrics.

What would you define as the most accurate forecast?



Mean Absolute Error = 9.18 K
Mean Bias Error = 6.71 K



Mean Absolute Error = 13.08 K
Mean Bias Error = 1.69 K

How can we assess how accurately a model is predicting cloud features when traditional metrics can be biased by non-cloud features or displacement?

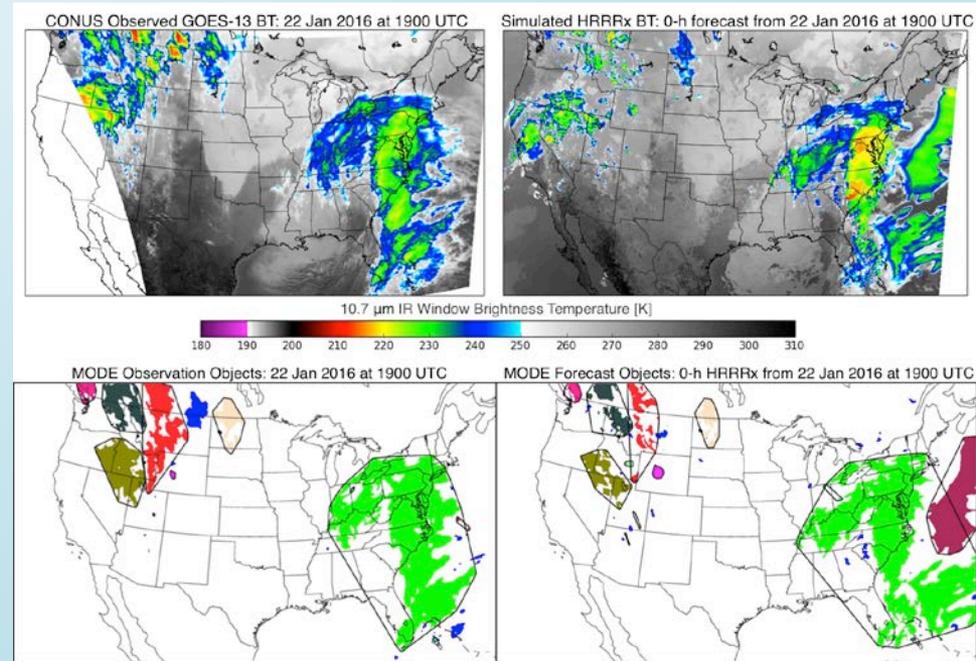
Object-Based Tracking

Program called method for object-based diagnostic evaluation
(**MODE**)

MODE identifies and matches objects in two different fields.

- 1) Smooth and threshold the forecast and observed Brightness Temperature (BT) fields.
 - BTs colder than a certain threshold
 - Objects of a minimum size.
- 2) Calculate various object attributes for each observed and forecast cloud object.
- 3) Match forecast and observed cloud objects using a fuzzy-logic algorithm and calculate attributes of paired objects, such as intersection area and distance.
- 4) Output attributes for individual objects and matched object pairs for assessment.

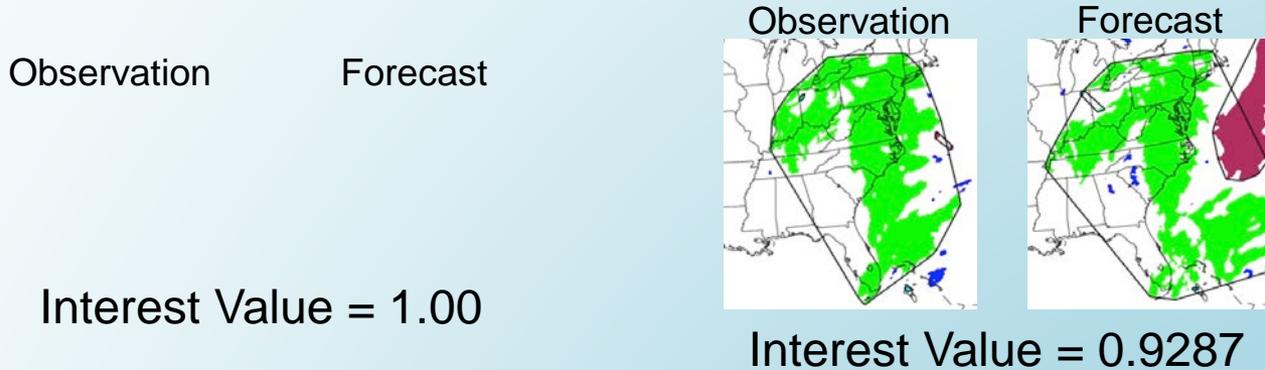
MODE



Circled objects represent clusters. One or more objects can be in a cluster.
Useful if one or more object from one field matches up with a single object in the other.

MODE: How well do objects match?

MODE measures the correspondence between two objects by computing the **interest value** between matched objects.



Interest Value is a weighted average of attribute interest values.

| Attribute | Weight | Description |
|----------------------------|------------|---|
| Centroid Boundary Distance | 4 (25%) | Distance between objects' centers of mass |
| Boundary Distance | 3 (18.75%) | Minimum distance between the objects |
| Convex Hull Distance | 1 (6.25%) | Minimum distance between the polygons surrounding the objects |
| Angle Difference | 1 (6.25) | Orientation-angle difference |
| Area Ratio | 4 (25%) | Ratio of the forecast and observation objects' areas (lowest value) |
| Intersection Area Ratio | 3 (18.75%) | Ratio of the observation (forecast) object to the objects' intersection area (lowest value) |

MODE Composite Score (MCS)

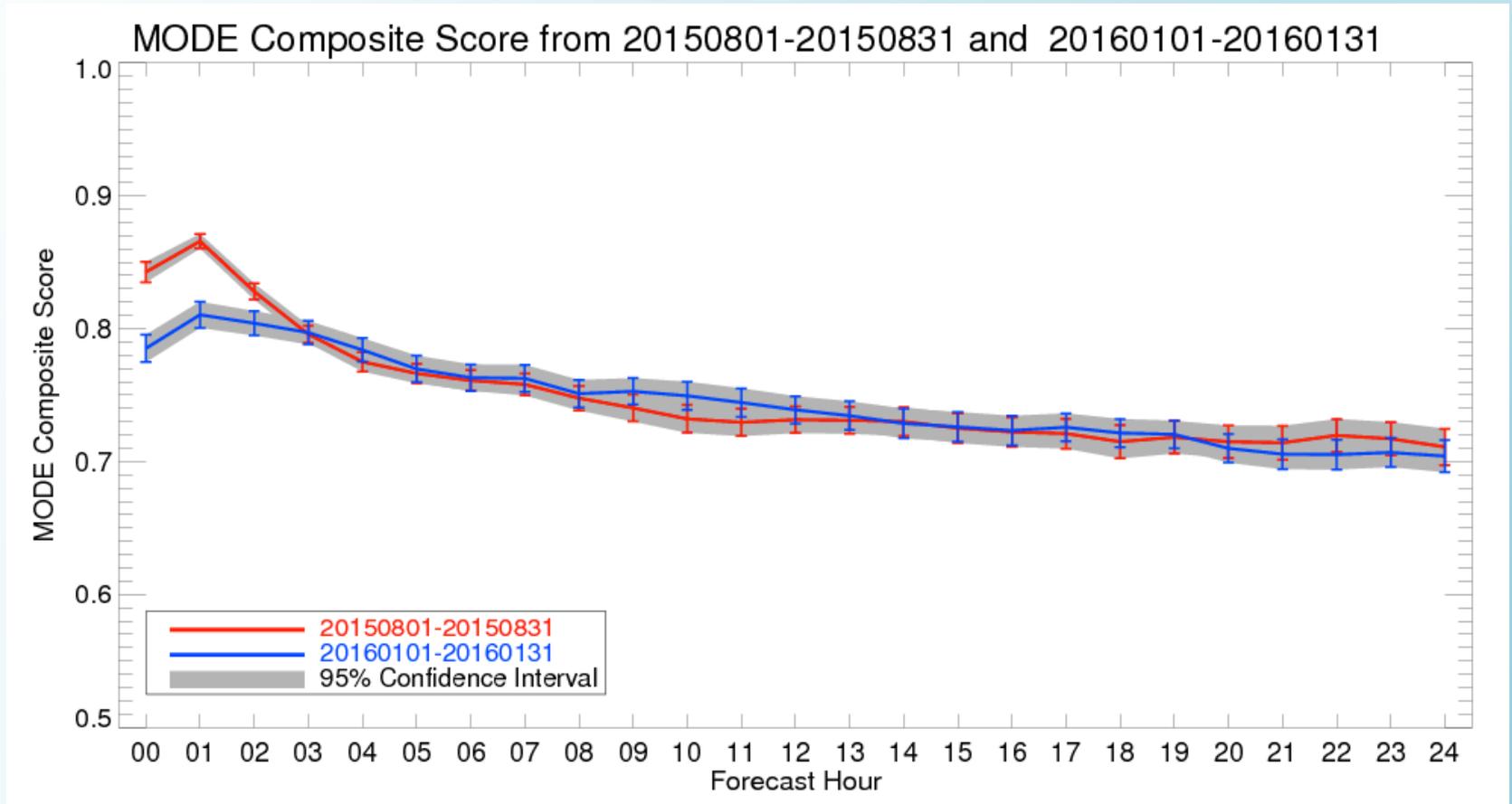
Combines wealth of information about objects into a single value

$$\text{MCS} = \sum_{i=1}^c \frac{\text{Area}_{\text{Observed Cluster}(i)}}{\text{Total Area}} * \text{Interest Value}(i) + \sum_{j=1}^o \frac{\text{Area}_{\text{Observed Object}(j)}}{\text{Total Area}} * \text{Interest Value}(j)$$

- Area-weighted metric that uses the MODE interest values for each object
- Area weighting used so that more weight is given to larger cloud objects
- Total Area = observation area + unmatched forecast area
- Area of each object or cluster multiplied by its interest value and then summed over all identified objects and clustered
- MODE Composite Score ranges from 0 to 1.
 - Zero indicates no skill
 - One indicates perfect skill

Results

Compared experimental HRRR simulated BT to GOES observed BT for August 1-30, 2015 and January 1-31, 2016.



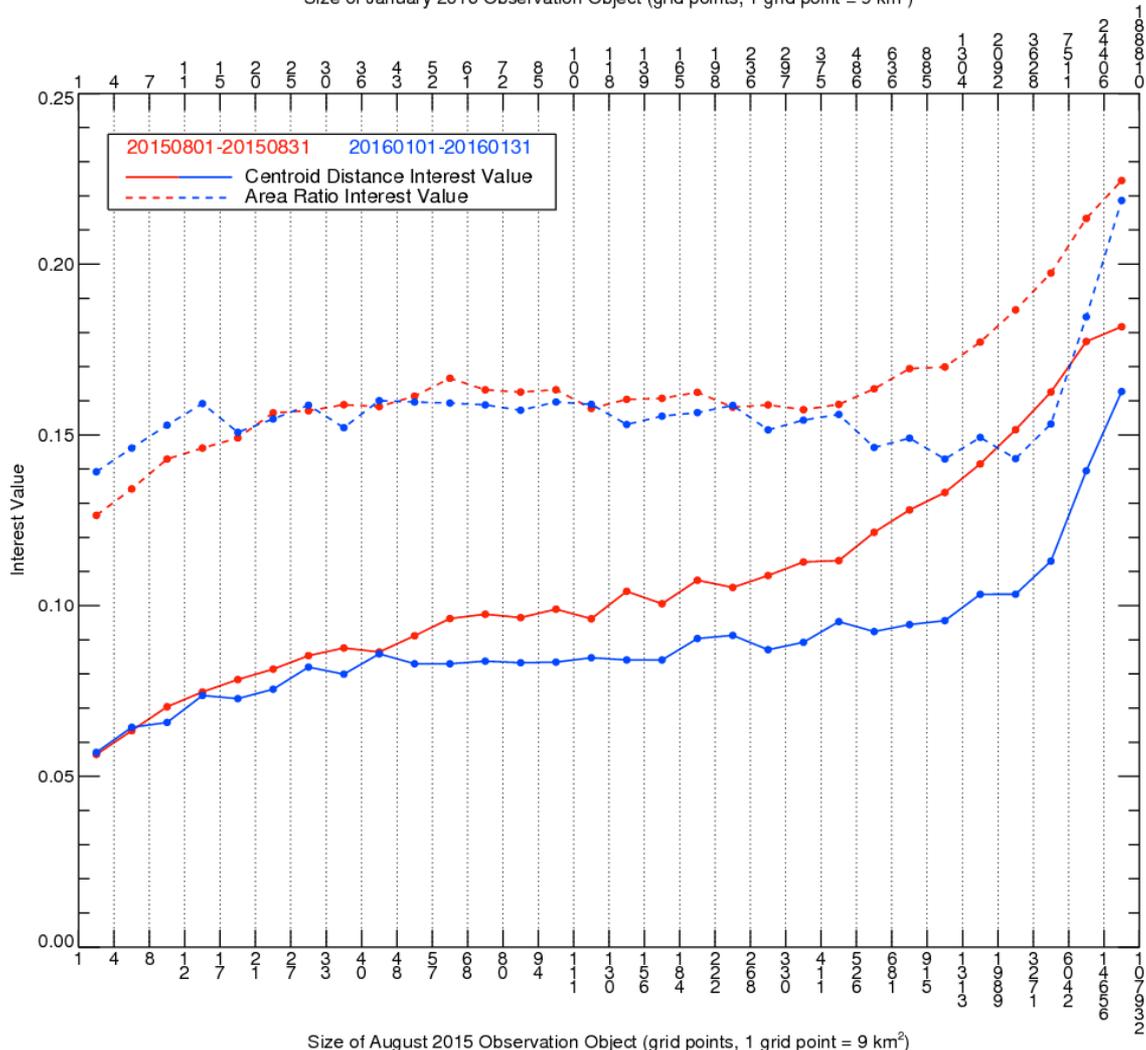
Why are the forecasts from August more accurate than the January forecasts for early hours?

Why is the 1-h forecast more accurate than the 0-1 forecast?

August more skillful than January

Comparison between Object Sizes and Attribute Interest Scores for 20150801-20150831 and 20160101-20160131 for FH01

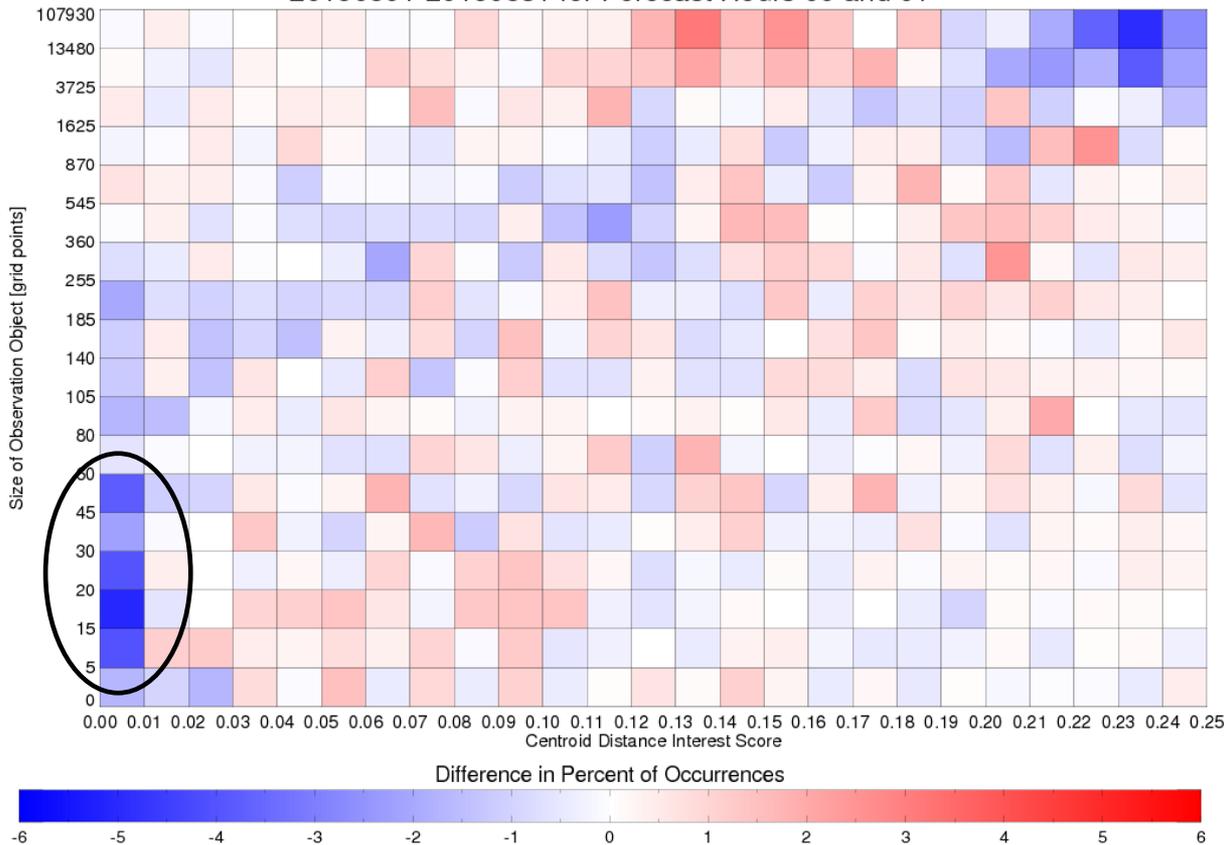
Size of January 2016 Observation Object (grid points, 1 grid point = 9 km²)



1-h forecast more skillful than 0-h analysis

$$\text{Difference in Percent of Occurrences} = \frac{\text{Number}(\text{score}, \text{size})_{\text{FH 00}}}{\text{Total}(\text{size})_{\text{FH 00}}} - \frac{\text{Number}(\text{score}, \text{size})_{\text{FH 01}}}{\text{Total}(\text{size})_{\text{FH 01}}}$$

Centroid Distance and Observation Object Sizes Combinations for 20150801-20150831 for Forecast Hours 00 and 01



Greater Occurrence
For Forecast Hour 1

Greater Occurrence
For Forecast Hour 0

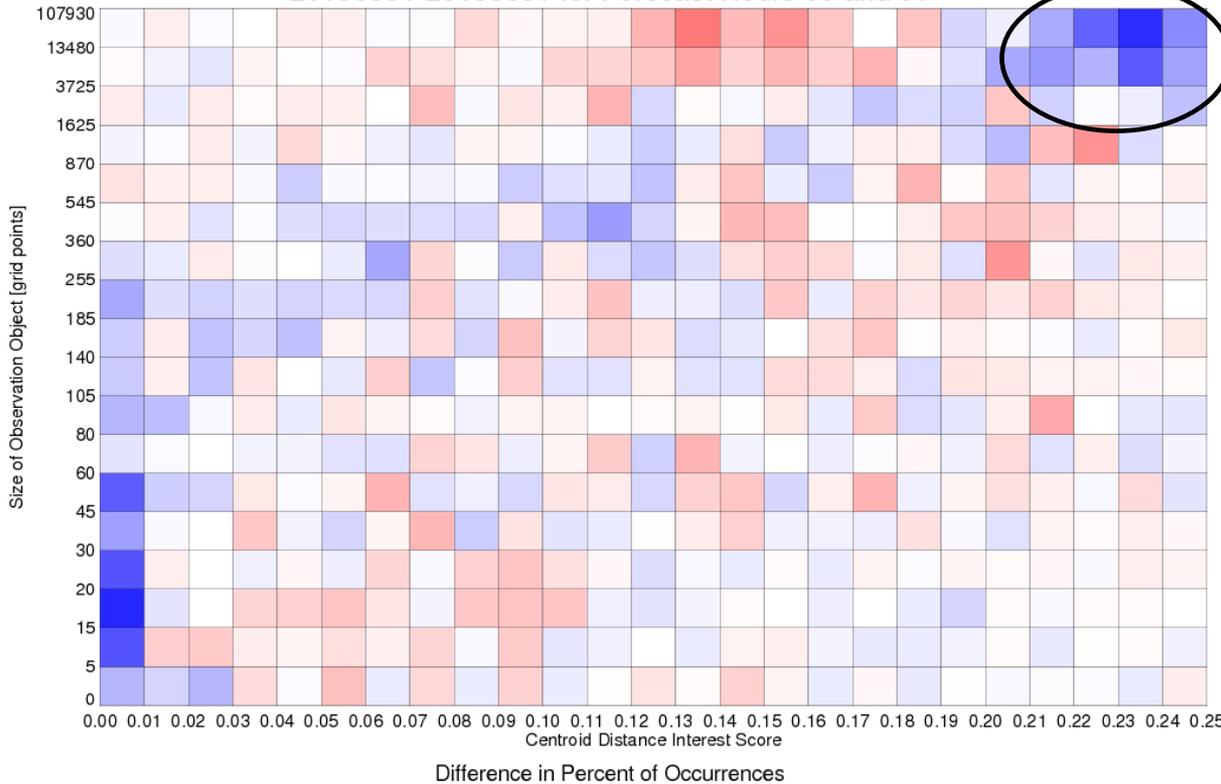
Centroid distance:
distance between the
center points of objects

- For small objects, more forecast hour 1 objects have low interest scores

1-h forecast more skillful than 0-h analysis

$$\text{Difference in Percent of Occurrences} = \frac{\text{Number}(\text{score, size})_{\text{FH 00}}}{\text{Total}(\text{size})_{\text{FH 00}}} - \frac{\text{Number}(\text{score, size})_{\text{FH 01}}}{\text{Total}(\text{size})_{\text{FH 01}}}$$

Centroid Distance and Observation Object Sizes Combinations for 20150801-20150831 for Forecast Hours 00 and 01



Greater Occurrence
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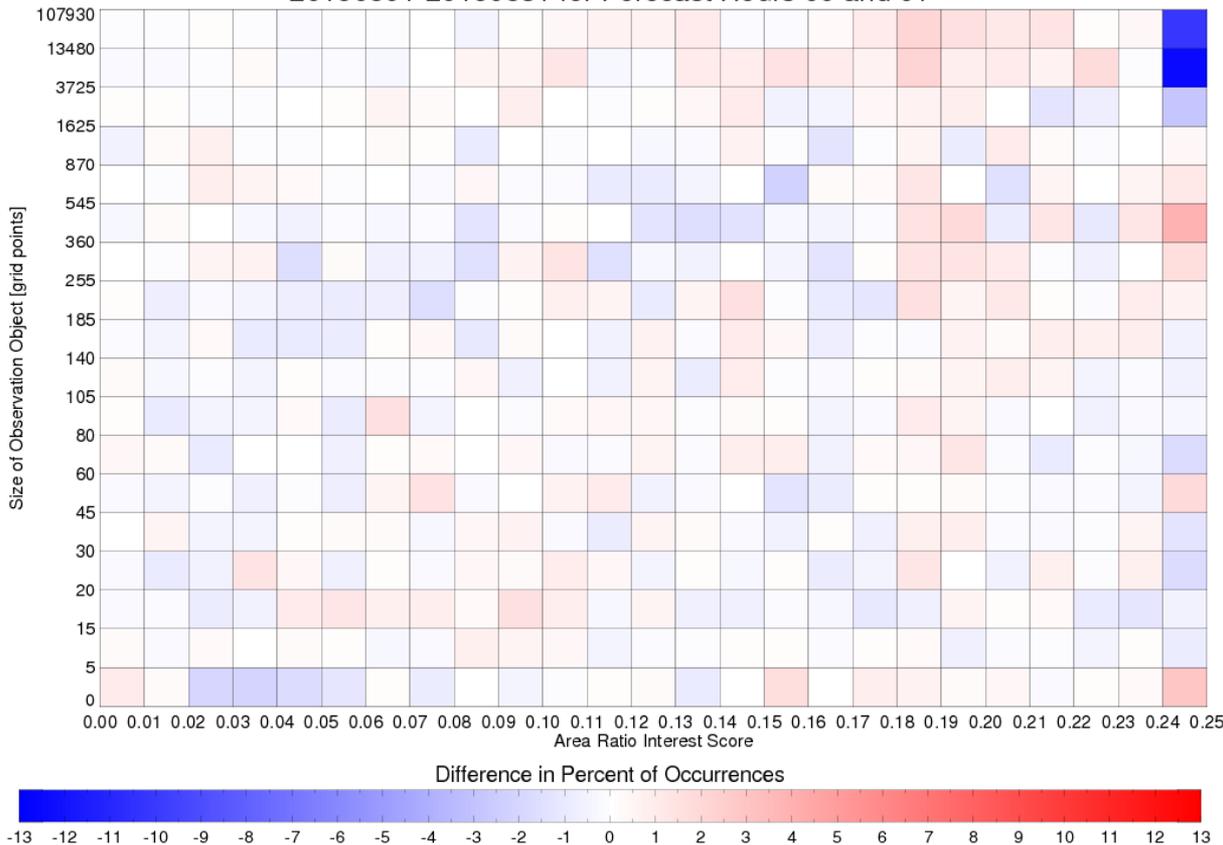
Centroid distance:
distance between the
center points of objects

- For small objects, more forecast hour 1 objects have low interest scores
- For larger objects, more forecast hour 1 objects have larger interest scores
- Improvement in larger objects has a greater impact on the MODE Composite Score

1-h forecast more skillful than 0-h analysis

$$\text{Difference in Percent of Occurrences} = \frac{\text{Number}(\text{score}, \text{size})_{\text{FH 00}}}{\text{Total}(\text{size})_{\text{FH 00}}} - \frac{\text{Number}(\text{score}, \text{size})_{\text{FH 01}}}{\text{Total}(\text{size})_{\text{FH 01}}}$$

Area Ratio and Observation Object Sizes Combinations for 20150801-20150831 for Forecast Hours 00 and 01



Greater Occurrence
For Forecast Hour 1

Greater Occurrence
For Forecast Hour 0

Area ratio: ratio of the number of observed to forecast grid points

- Small differences for most interest scores and object sizes
- For larger objects, higher percentage of forecast hour 1 object matches have larger interest scores
- Improvement in large cloud objects has a greater impact on the MODE Composite Score

Conclusions

We described object-based statistics package called MODE which was used to assess the accuracy of experimental HRRR cloud cover (using brightness temperatures as a proxy).

MODE is highly configurable, allowing users to decide the threshold and minimum size of objects as well as what is most important when defining object matches.

We've developed a metric (MODE Composite Score) to distill all of the information from MODE into a single value.

Forecast accuracy can all be assessed using object or attribute interest scores, which can better explain **WHY** one forecast is more accurate than the other.