

The Contribution of Locally Generated MTSat-1R. **Atmospheric Motion** Vectors to Operational Meteorology in the Australian Region





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Overview

- The Challenge
- CAWCR
- The Satellite Program
- Recent Data Impact Studies
- MTSaT-1R Data Impact/error Characterization Studies
- Plans/Future Prospects
- Summary







Anomaly correlation for days 0 to 7 for 500 hPa geopotential height in the zonal band 20°-80° for January/February. The red arrow indicate use of satellite data in the forecast model has doubled the length of a useful forecast.





CAWCR

The Centre for Australian Weather and Climate Research





Atmosphere-Land Observation & Assessment

- Atmospheric composition
 - gases
 - aerosol
- Cloud, radiation and precipitation processes
- Biogeochemical cycles (carbon & water)
- Micrometeorology
- Observing system technologies
- Remote sensing and data assimilation







Australian Government Bureau of Meteorology



Centre for Australian Weather and Climate Research: a partnership between CSIRO and the Bureau of Meteorology

Scope of the Australian Community Climate and Earth System Simulator (ACCESS)



SOME RECENT ADVANCES / DATA IMPACT

STITLER FOR SATELLITE DATA

ASA JCSDA Navy



OBSERVING SYSTEM EXPERIMENTS

OBSERVING SYSTEM EXPERIMENTS WITH SATELLITE AND CONVENTIONAL DATA



Fig. 6. Anomaly correlation for days 0 to 7 for 500 hPa geopotential height in the zonal band 20°-80° for each Hemisphere and season. The control simulation is shown in blue, while the NoSat and NoCon denial experiments are shown in magenta and green, respectively.



Fig. 7 The impact of removing satellite and in-situ data on hurricane track forecasts in the GFS during the period 15 August to 20 September 2003. Panels (a and b) show the average track error (NM) out to 96 hours for the control experiment and the NoSat and NoCon denials for the Atlantic and Pacific Basins, respectively.



OBSERVING SYSTEM EXPERIMENTS

OBSERVING SYSTEM EXPERIMENT WITH FOUR SATELLITE DATA TYPES AND RAWINSONDE DATA



Fig. 8 The day 5 anomaly correlations for waves 1-20 for the (a and d) mid-latitudes, (b and e) polar regions and (c and f) tropics. Experiments shown for each term include, from left to right, the control simulation and denials of AMSU, HIRS, GEO winds, Rawinsondes and QuikSCAT. The 15 January to 15 February 2003 results are shown in the left column and the 15 August to 20 September results are shown in the right column. Note the different vertical scale in (c and f).



Fig. 9. The 15 January to 15 February 2003 day 0-7 500 hPa geopotential height die-off curves for the control and five denial experiments. The Northern Hemisphere results are shown in the left panels and the Southern Hemisphere results are shown in the right panels.



Fig. 10. Average track error (NM) by forecast hour for the control simulation and experiments where AMSU, HIRS, GEO winds and QuikSCAT were denied. The Atlantic Basin results are shown in (a), and the Eastern Pacific Basin results are shown in (b). A small sample size in the number of hurricanes precludes presenting the 96 hour results in the Eastern Pacific Ocean.



MODIS Wind Assimilation into the NCEP Global Forecast System

Global Forecast System Background

- Operational SSI (3DVAR) version used
- Operational GFS T254L64 with reductions in resolution at 84 (T170L42) and 180 (T126L28) hours. 2.5hr cut off

The Trial



• Winds assimilated only in <u>second last analysis</u> (later "final" analysis) to simulate realistic data availability.

Table 1: Satellite data used operationally within theGMAO/NCEPGlobal Forecast System

HIRS sounder radiances
AMSU-A sounder radiances
AMSU-B sounder radiances
GOES sounder radiances
GOES 9,10,12, Meteosat
atmospheric motion vectors
GOES precipitation rate
SSM/I ocean surface wind speeds
SSM/I precipitation rates

TRMM precipitation rates ERS-2 ocean surface wind vectors Quikscat ocean surface wind vectors AVHRR SST AVHRR vegetation fraction AVHRR surface type Multi-satellite snow cover Multi-satellite sea ice SBUV/2 ozone profile and total ozone **Table 1: Comparison of radiosonde wind estimates with Terra and Aqua based MODIS AMVs, colocated within 150km over high latitudes for the period 5 May 2005 to 10 January 2006 inclusive, where the AMV QI** \geq 0.85. [IR = 11µm based winds, WV = 6.7 µm based **winds and MMVD = mean magnitude of vector difference** (ms⁻¹)].

Туре		AQUA IR	AQUA WV	TERRA IR	TERRA WV
Low	No. of Obs.	142	N/A	80	N/A
999- 700hPa	MMVD (ms ⁻¹)	3.92	N/A	3.58	N/A
	RMS Vec. Diff. (ms ⁻¹)	4.57	N/A	4.02	N/A
	Speed Bias (ms ⁻¹)	-0.30	N/A	-0.03	N/A
Middle 699- 400HPa	No. of Obs.	342	558	287	485
	MMVD (ms ⁻¹)	4.38	4.34	4.20	4.30
	RMS Vec. Diff. (ms ⁻¹)	4.93	4.90	4.79	4.85
	Speed Bias (ms ⁻¹)	-1.01	-0.72	-0.35	-0.24
High 399- 150hPa	No. of Obs.	106	358	76	345
	MMVD (ms ⁻¹)	4.71	4.96	4.81	4.28
	RMS Vec. Diff. (ms ⁻¹)	5.22	5.55	5.26	4.83
	Speed Bias (ms ⁻¹)	-0.80	-0.65	-0.50	-0.34



Fig 1 (a) Distribution of levels of best fit compared to a collocated radiosonde profile for AMVs with pressure altitudes in the ranges 500 ± 50 hPa (Mid-level), 300 ± 50 hPa (High level) and , 850 ± 50 hPa (Low level). In all cases, the AMV QI is in the range 0.85 to 1.0.



Fig 1 (b) Distribution of levels of best fit compared to a collocated radiosonde profile for AMVs with pressure altitudes in the ranges 500 ± 50 hPa (mid-level), 300 ± 50 hPa (high level) and , 850 ± 50 hPa (low level). In all cases, the AMV EE is less than 5 m/s.



Fig. 2 (a) Error Correlation versus distance (using 10 km bins), determined by comparison with radiosonde winds, for MODIS WV Mid-level Vectors (Northern Hemisphere, May 2005 – Jan 2006)

Table 2 (a) Parameters of the SOAR function (Equation 1) which best model the measured error correlations for the MODIS AMV types listed in the left column of the table. (QI = 0.65 to 1)

Туре	R ₀₀	R ₀	L (km)	Corr. Err. (ms ⁻¹)	RMSD (ms⁻ ¹)
Low IR	- 0.029	0.6 8	128. 9	3.01	4.51
Mid IR	- 0.010	0.8 2	113. 1	4.16	5.07
High IR	0.029	0.7 8	117. 7	4.28	5.49
Mid WV	0.010	0.8 5	95.3	4.29	5.05
High WV	- 0.051	0.9 1	107. 6	4.83	5.31

Table 2 (b) Parameter of the SOAR function (Equation 1) which best model the measured error correlations for the MODIS AMV types listed in the left column of the table. R_{00} is assumed to be 0. (QI = 0.65 to 1)

Туре	R ₀₀	R ₀	L	Corr. Err. (ms ⁻	RMSD (ms ⁻¹)
			(KM)	')	
Low IR	0	0.77	123.6	3.47	4.51
Mid IR	0	0.84	120.3	4.26	5.07
High IR	0	0.83	98.6	4.56	5.49
Mid WV	0	0.89	100.4	4.49	5.05
High WV	0	0.95	100.8	5.04	5.31



Fig. 3. The 500 hPa geopotential height Anomaly Correlation for the Northern Hemisphere polar Region (60° N – 90° N), for the GFS control and the GFS control including MODIS AMVs, for the period 10 August to 23 September 2004.



Fig. 5. The 500hPa geopotential height anomaly correlation for the Southern Hemisphere polar region (60° S – 90° S), for the GFS control and the GFS control including MODIS AMVs, for the period 1 January to 15 February 2004.

2004 ATLANTIC BASIN AVERAGE HURRICANE TRACK ERRORS (NM)

13.2	43.6	66.5	94.9	102.8	157.1	227.9	301.1	Cntrl
11.4	34.8	60.4	82.6	89.0	135.3	183.0	252.0	Cntrl + MODIS
74	68	64	61	52	46	39	34	Cases (#)
00-h	12-h	24-h	36-h	48-h	72-h	96-h	120-h	Time

Results compiled by Qing Fu Liu.

The Contribution of Locally Generated MTSat-1R Atmospheric Motion Vectors

to

Operational Meteorology

in the Australian Region

MTSaT-1R IR1 AMVs

Uses 3 images separated by 15 min. or 60 min.

Uses H₂0 intercept method for upper level AMVs (Schmetz et al., 1993) or Window Method.

Uses cloud base assignment for lower level AMVs (Le Marshall et al. 1997) or Window Method

Q.C. via EE, QI, ERR, RFF etc.

No autoedit

Table 1. Real time schedule for MTSat-1R Atmospheric MotionVectors at the Bureau of Meteorology. Sub-satellite imageresolution, frequency and time of wind extraction andseparations of the image triplets used for wind generation (//T)are indicated.

Wind Type	Resolution	Frequency-Times (UTC)	Image Separation
Real Time IR	4 km	6-hourly – 00, 06, 12, 18	15 minutes
Real Time IR (hourly)	4 km	Hourly – 00, 01, 02, 03, 04, 05, , 23	1 hour



Fig. 1 (a) MTSat-1R AMVs generated around 12 UTC on 18 March 2007. Magenta denotes upper level tropospheric vectors, yellow, lower level tropospheric vectors


Fig. 1 (b) A selection of MTSat-1R AMVs generated around 12 UTC on 18 March 2007. Magenta denotes upper level tropospheric vectors (above 500 hPa), yellow, lower level tropospheric vectors (below 500 hPa)









ERROR CHARACTERIZATION OF ATMOSPHERIC MOTION VECTORS

QUALITY CONTROL

QUALITY CONTROL

- **Several components to quality control process**
- **ERR:** Wind data accepted and errors assigned, in conjunction with several rejection criteria, including :
 - * Correlation between images
 - * U acceleration
 - * V acceleration
 - * U component deviation from guess
 - * V component deviation from guess

•••••

QI

EXPECTED ERROR

*

Quality Control



Considers

Correlation between images U acceleration V acceleration U deviation from first guess V deviation from first guess

Quality Indicator (QI)

Considers

Direction consistency (pair)
Speed consistency (pair)
Vector consistency (pair)
Spatial Consistency
Forecast Consistency

 $QI = \sum w_i . QV_i / \sum w_i$

Fig.3. Quality Indicator (QI) versus root mean square difference (RMSD) with radiosondes within 150 km for low level high-resolution visible image based AMVs for 28 April, 2000 to 29 April 2001.



EE - provides RMS Error (RMS)

In current ops. currently estimated from: the five QI components, wind speed vertical wind shear, temperature shear, pressure level which are used as predictands for root mean square error

Other statistical and physical calculation methods have been tested

EE (RMS Error (RMS))

Is inserted into current NESDIS BUFR (in test mode) using

QualityFlag(EE) = (100 - 10.0 * EE)



Fig. 2 (a) Measured error (m/s) versus EE for high-level MTSAT-1R IR winds (13 March - 12 April 2007



Fig. 2 (b) Measured error (m/s) versus EE for lowlevel MTSAT-1R IR winds (13 March - 12 April 2007)

Table 2. Mean Magnitude of Vector Difference (MMVD) betweenMTSat-1R AMVs, forecast model first guess and radiosondewinds within 150 km for March 2007

Level	No. of Obs	First Guess MMVD (ms ⁻¹)	AMV MMVD (ms ⁻¹)
Low 950 – 700 hPa	192	2.67	2.92
Middle 699 – 400 hPa	88	3.79	3.75
High 399 – 150 hPa	706	4.13	4.08

Table 5.2: AMV numbers and comparative errors in predicted error when selecting upper level WV AMVs (November 2002) using EE and QI. Vector samples here are chosen with average MMVD equal to 5 and 6 ms⁻¹ respectively. (From Le Marshall et al. (2004a))

	EE	QI	EE	QI
Threshold	$\mathrm{EE} < 5.2$	QI>.98	EE<8.5	QI>.89
No. of matches	3156	514	7265	2863
Av. MMVD	5.00	5.00	6.0	6.0
Av. error in predicted error	3.17	5.24	3.25	4.31

Correlated Error

Correlated error

The correlated error has been analysed for the Bureau produced MTSat-1R winds. The methodology was similar to that followed previously (Le Marshall et al., 2004). The correlated error and its spatial variation (length scale) were determined using the Second Order Auto Regressive (SOAR) function :

$$\mathbf{R}(\mathbf{r}) = \mathbf{R}_{00} + \mathbf{R}_{0}(1 + \mathbf{r}/\mathbf{L}) \exp(-\mathbf{r}/\mathbf{L})$$
(2)

Where $\mathbf{R}(\mathbf{r})$ is the error correlation, \mathbf{R}_0 and \mathbf{R}_{00} are the fitting parameters (greater than 0), L is the length scale and r is the separation of the correlates. The difference between AMV and radiosonde winds (error) has been separated into correlated and non-correlated parts. A typical variation of error correlation with distance for MTSat-1R IR1 AMVs is seen in Figure 3, while the parameters of the SOAR function which best fits the observations are contained in Table 3.

Fig. 3 Error correlation versus distance (100 km bins) for low-level MTSat-1R AMVs with EE < 6 and 8 m/s (March – July 2007)



Table 3. Parameters of the SOAR function (Equation 2) which best model themeasured error correlations for the MTSat-1R AMVs listed in the left column ofthe table. (February – April, 2007)

MTSat-1R IR1 AMVS	R ₀₀		R ₀		L (km)	
	Low	High	Low	High	Low	High
EE < 6	0.006	0.370	0.460	0.460	86.000	99.900
EE < 8	0.066	0.052	0.640	0.440	122.700	110.900

MTSaT-1R DIRECT READOUT AMV GENERATION AND RT ASSIMILATION

MTSaT-1R at 140°E 0°S from 2005

Ch2 (IR1) AMVs generated in RT

RT trial 30 May - 15 June 2007 – 30 cases Trial used then operational RT LAPS 375 51 levels

RT trial 1 Sept. - 8 Aug. 2007 – 72 cases Trial used now operational RT LAPS 375 61 levels

Local AMVs subsequently accepted for operational use.

RTMTSaT-1R IR1 AMVs

Used 3 images separated by 15 min. or 60 min.

Used H₂0 intercept method for upper level AMVs (Ch3/4) (Schmetz et al., 1993) or Window Method.

Used cloud base assignment for lower level AMVs (Ch4) (Le Marshall et al. 1997) or Window Method.

Q.C. via EE, QI, ERR, RFF etc.

No autoedit

OPERATIONAL TRIAL

30 May – 15 June 2008

Used

- * Real Time Local Satellite Winds
- ~ 2 sets of IR1 quarter hourly motion vectors every six hours.
- * Operational Regional Forecast Model (L51)and Data Base (Inc JMA AMVs)
- * Operational Regional Verification Grid



Table 4. Mean Magnitude of Vector Difference (MMVD) and Root Mean Square Difference (RMSD) between MTSat-1R AMVs, forecast model first guess winds and radiosonde winds for the period 30 May to 15 June 2007

Level	Data Source	Bias (ms ⁻¹)	No. of Obs	MMVD (ms ⁻¹)	RMSVD (ms ⁻¹)	
High – up to 150 km	AMVs	-0.55	1386	3.90		4.47
separation between radiosondes and AMVs	First Guess	1.3776	1386	4.42		5.09
Low - up to 150 km	AMVs	-0.76	540	3.18		3.72
separation between radiosondes and AMVs	First Guess	-0.70	540	2.72		3.12
Low – up to 30 km	AMVs	-0.44	18	2.45		3.08
separation between radiosondes and AMVs	First Guess	-0.20	18	2.67		3.07

Accepted/Rejected Observations for LAPS model based on Wind Spd/Dir WMC/RTH Melbourne Date: 20071216 at cycle 3 analysis 00Z (extracted at 00:49 UTC)

AMV cycle3_standard00Z



Table 5 (a) 24 hr forecast verification S1 Skill Scoresfor the May 2007 operational regional forecast system(L51 LAPS) and L51 LAPS with IR, 6-hourly imagebased AMVs for 30 May to 15 June 2007 (34 cases)

LEVEL	(LAPS) S1	(LAPS + MTSAT-1R AMVS) S1
MSLP	19.00	18.81
1000 hPa	21.35	20.80
900 hPa	22.42	22.08
850 hPa	22.81	22.76
500 hPa	15.96	15.91
300 hPa	13.65	13.65
250 hPa	12.62	12.58

OPERATIONAL TRIAL

1 September – 8 October 2008

Used

- * Real Time Local Satellite Winds
- ~ 2 sets of IR1 quarter hourly motion vectors every six hours.
- * Operational Regional Forecast Model (L61)and Data Base (Inc JMA AMVs)
- * Operational Regional Verification Grid



Table 5 (b) 24 hr forecast verification S1 SkillScores for the next operational regional forecastsystem (L61 LAPS) and L61 LAPS with IR, 6-hourlyimage based AMVs for 1 September to 8 October2007 (72 cases)

LEVEL	(LAPS) S1	(LAPS + MTSAT-1R AMVS) S1
MSLP	20.24	19.15
1000 hPa	20.06	19.13
900 hPa	18.65	17.75
850 hPa	17.41	16.69
500 hPa	12.41	11.73
300 hPa	10.49	9.76
250 hPa	12.41	11.90

Table 5 (a) 24 hr forecast verification S1 SkillScores for the May 2007 operational regionalforecast system (L51 LAPS) and L51 LAPS withIR, 6-hourly image based AMVs for 30 May to 15June 2007 (34 cases)		Table 5 (b) 24 hr forecast verification S1 SkillScores for the next operational regional forecastsystem (L61 LAPS) and L61 LAPS with IR,6-hourly image based AMVs for 1 September to 8October 2007 (72 cases)			
LEVEL	(LAPS) S1	(LAPS + MTSAT-1R AMVS) S1	LEVEL	(LAPS) S1	(LAPS + MTSAT- 1R AMVS) S1
MSLP	19.00	18.81	MSLP	20.24	19.15
1000 hPa	21.35	20.80	1000 hPa	20.06	19.13
900 hPa	22.42	22.08	900 hPa	18.65	17.75
850 hPa	22.81	22.76	850 hPa	17.41	16.69
500 hPa	15.96	15.91	500 hPa	12.41	11.73
300 hPa	13.65	13.65	300 hPa	10.49	9.76
250 hPa	12.62	12.58	250 hPa	12.41	11.90

The Transition from MTSaT–1R HIRID Format to HRIT Format

02:30 UTC 12 March 2008

HRIT IR1 AMV/RAOB Comparison: 24 January – 20 February, 2008 v1 15min.						
Wind Level	LOW E	ERR=0,EI	E<3.5		High ER	R=0,QI=.6-1.
Wind Type	AMV	AMV Background				Background
RAOB/AMV Sep	75	150	75	150	150	150
No of Vectors	53	264	53	264	2953	2953
Bias m/s	0.27	0.3	-0.26	28	-0.05	-0.92
MMVD	2.40	2.83	2.56	2.73	4.04	4.17
RMS VD m/s	2.72	3.24	2.76	3.08	4.59	4.81

HRIT IR1 AMV/RAOB Comparison: 24 January – 20 February, 2008 v2 15min.						
Wind Level	LOW B	LOW ERR=0,EE<3.5 High ERR=0,QI=.6-1.				
Wind Type	AMV	AMV Background			AMV	Background
RAOB/AMV Sep	75	150	75	150	150	150
No of Vectors	53	264	53	264	3254	3254
BIAS m/s	-0.08	-0.21	-0.26	-0.28	0.80	-1.07
MMVD m/s	2.22	2.71	2.56	2.73	3.82	4.28
RMS VD m/s	2.53	3.12	2.76	3.08	4.41	4.92

HRIT AMVs – Pre-implementation Operational Test

Operational TLAPS S1 Scores versus Operational TLAPS plus HRIT IR1 Atmospheric Motion Vectors (AMVs)-Feb 21 –March-10 (17 Cases)

	Ops.	Ops. + HRIT
MSLP	24.76	24.29
1000 hPa	24.47	24.17
850hPa	23.88	23.47
500 hPa	18.23	17.88
300 hPa	16.88	16.70
250 hPa	15.76	15.52

- ACCESS UKUM
- Global and Regional Impact Studies
- Use of Continuous Data- Hourly AMVs in 4D-VAR

eg.TC Nicholas Western Australian region February 2008

- ACCESS UKUM
- Global and Regional Impact Studies



latitude0



latitude0



8

difference PRESSURE AT MEAN SEA LEVEL with/without AMV access 48hr forecast 29/03/08 12:00 Mean 0.394952 Max 6.73 Min -8.3

latitude0
The Future

• ACCESS – UKUM

 Use of Continuous Data- Hourly AMVs in 4D-VAR (Regional 37.5km)
eg.TC Nicholas Western Australian region February 2008









Local MTSat-1R JMA ESAC

Satwind.varobs.1 20080215 1200









The Future

- Cloud Height Assignment and Verification LBF, A-Train
- AMV Error Characterization
- Model Clouds
- Continuous data/4D-VAR
- Moisture tracking / 4D-VAR



Discussion and Conclusions

- Both the geo-stationery and polar orbiting satellitebased AMVs have been shown to make a significant contribution globally to operational analysis and forecasting.
- MODIS AMVs have been shown to make a positive contribution in polar, mid-latitude and tropical regions.
- MTSaT-1R AMVs have been generated at the Australian BoM and have been shown to provide significant benefits in the Australian region.
- The successful application of MTSaT-1R AMVs has been facilitated by the careful use of quality-control parameters such as the EE, ERR and QI.
- Assimilation studies with UKUM based ACCESS model underway and showing promising results.



Australian Government

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