



ESA's ADM-Aeolus Wind Lidar Mission

Getting Ready for Launch

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European Space Agency

International Winds Workshop 13, Monterey 26 June-01 July 2016

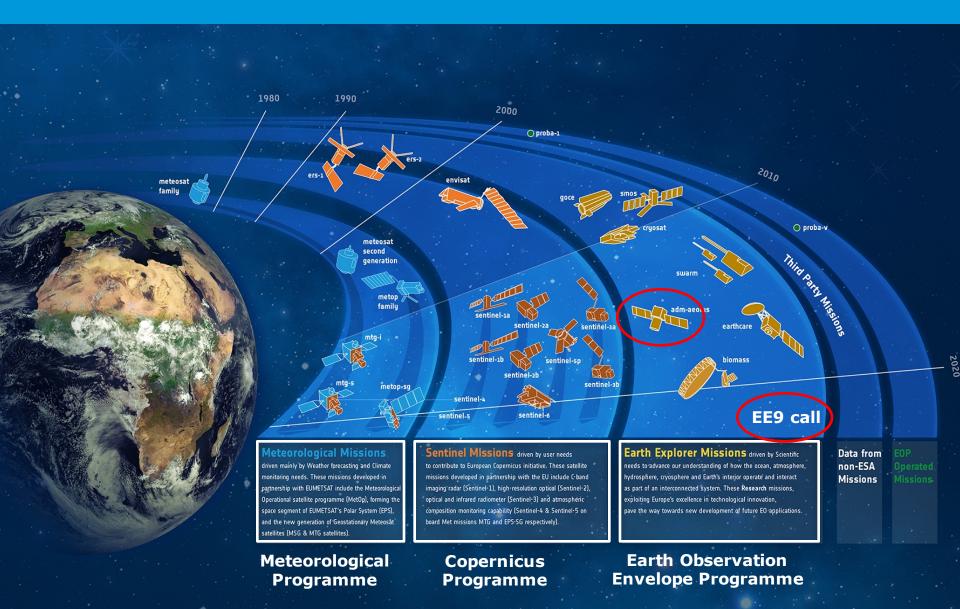
ADM-Aeolus teams



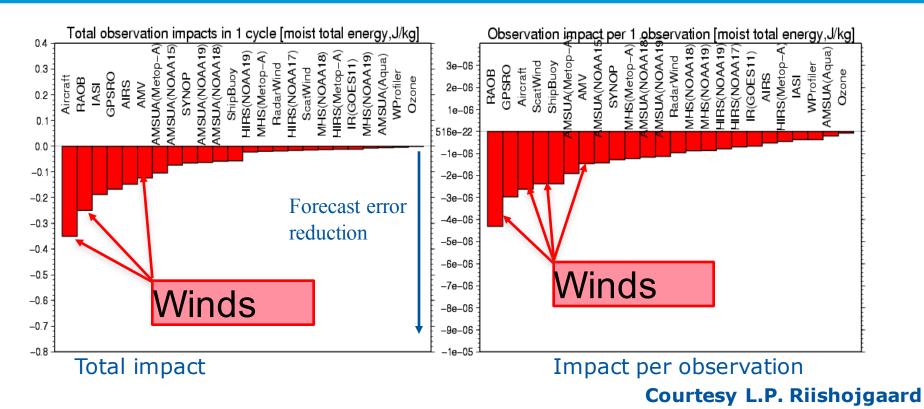
- ADM-Aeolus Project team
- Mission science and campaigns team
- PDGS and data quality teams
- Flight Operations Team
- Airbus Defence and Space & partners
- Aeolus Mission Advisory Group
- L1 and L2 algorithm development teams (DLR, DoRIT, ECMWF, KNMI, MeteoFrance)
- Campaign and CAL/VAL teams

ESA's Earth Observation Programme





WMO Workshop Sedona, May 2012 Assessment Global Observing System Impact

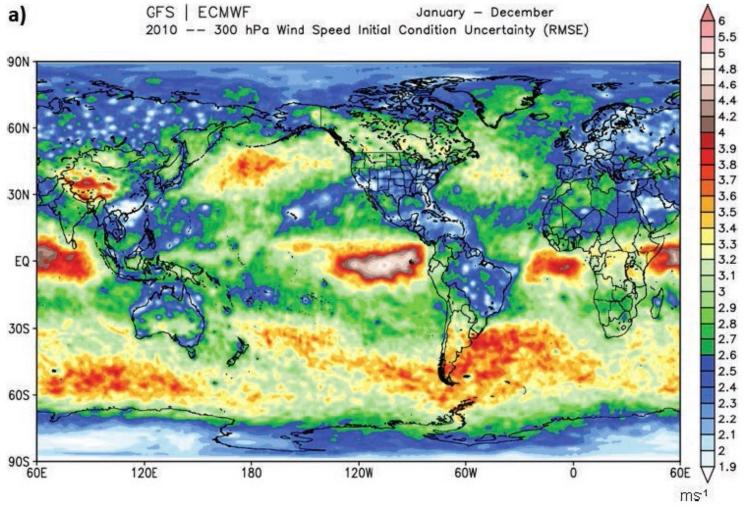


All observation types have positive **forecast impact** on average

Total impact: 1) <u>aircraft</u>, 2) AMSU-A, 3) <u>radiosonde</u>, 4) IASI, 5) GPSRO **Impact per observation:** 1) <u>radiosonde</u>, 2) GPSRO, 3) <u>aircraft</u>, 4) <u>scatterometer wind</u>, 5) marine surface observation

Differences in forecast reanalysis data



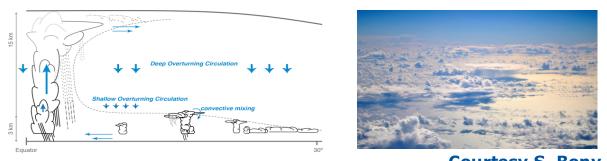


W. Baker et al., BAMS 2014

Examples - Importance of winds for climate



- 1. Atmospheric reanalyses for **climate model verification** need more wind observations
- 2. Grand Challenges of World Climate Research Programme are
 - a. Understanding the role of dynamically driven cloud circulation interactions for **climate sensitivity**

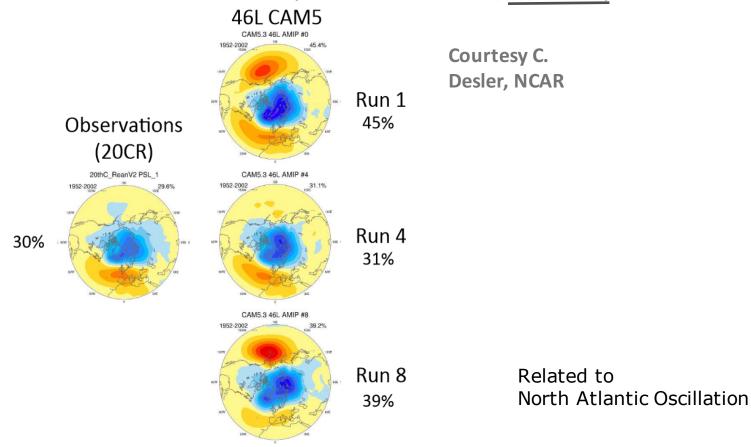


- Courtesy S. Bony, B. Stevens
 b. Understanding coupling of Tropospheric and Stratospheric dynamics and its impact on climate variability
- 3. Meridional transport of **ozone** is strongly impacted by tropical dynamics (e.g. convection -> gravity waves, planetary waves)

Importance for winds for climate applications



Understanding coupling Troposphere and Stratosphere dynamics and its impact on climate variability



Northern Annular Mode (EOF1 DJF SLP 20-90°N, 1952-2002)

ADM-Aeolus Mission Objectives



Scientific objectives

- To improve the quality of weather forecasts;
- To advance our understanding of atmospheric dynamics and climate processes;

Explorer objectives

 Demonstrate space-based Doppler Wind LIDARs potential for operational use.

Observation means:

 Provide global measurements of horizontal wind profiles in the troposphere and lower stratosphere

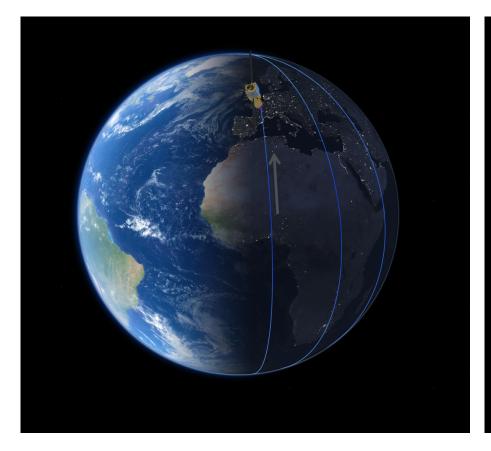
Payload

ALADIN: Atmospheric LAser Doppler INstrument



Mission characteristics



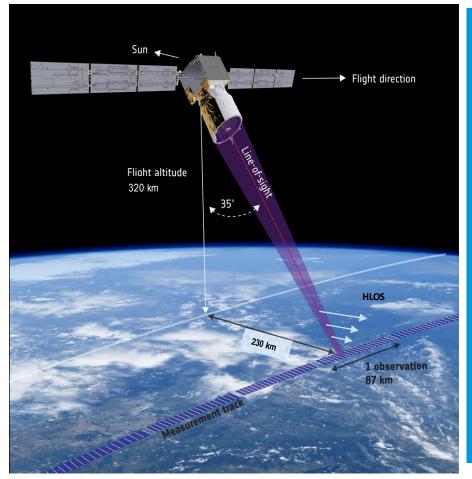


Mission Parameters

- Orbit: sun-synchronous
- Mean altitude: ~320 km
- Local time: 18:00 ascending node
- Inclination: 96.97°
- Repeat cycle: 7 days / 111 orbits
- ■Orbits per day: ~16

ADM-Aeolus Measurement Principle (1/2)



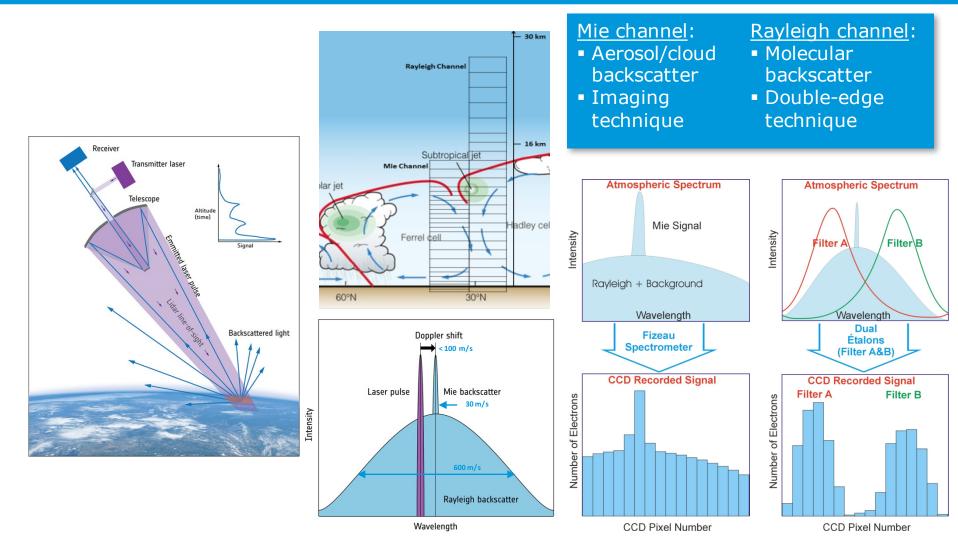


 UV Doppler wind Lidar operating at 355 nm and 50 Hz PRF in continuous mode, with 2 receiver channels (HSRL):

- Mie receiver (aerosol & cloud backscatter)
- Rayleigh receiver (molecular backscatter)
- The line-of-sight is pointing 35° from nadir to derive horizontal wind component
- The line-of-sight is pointing orthogonal to the ground track velocity vector to avoid contribution from the satellite velocity
- Spacecraft regularly pointed to nadir for calibration

Measurement Principle (2/2)

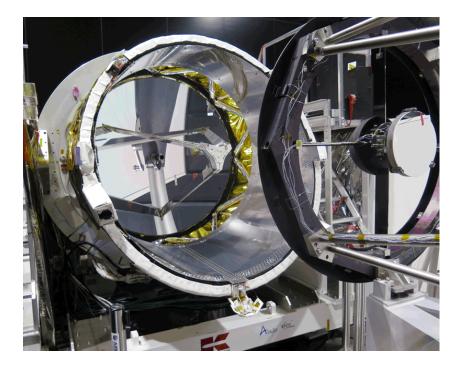




Instrument Status



- Instrument Full Functional Performance Test (IFP) April 2016
 - a. End-to-end testing in ambient conditions
 - Analysis on-going, preliminary results:
 - Random errors extrapolated from tests within 5% of expectations
 - detailed correlation analysis needed to confirm this (e.g. OGSE limitations)
 - Analysis of bias looks good
- 2. Instrument delivery: July 2016





- 1. Satellite platform ready for instrument integration
- 2. Instrument integration on platform: autumn 2016
- 3. Testing of instrument on platform: April 2017

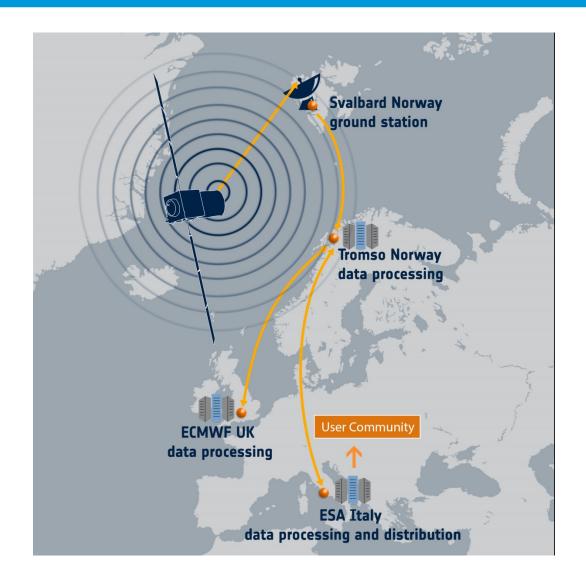
4. Satellite launch readiness: October 2017

- 5. Launch: at the earliest 6 weeks thereafter
- 6. Commissioning phase: L L+3 months

7. Operational Phase: L+3 months – 3 years

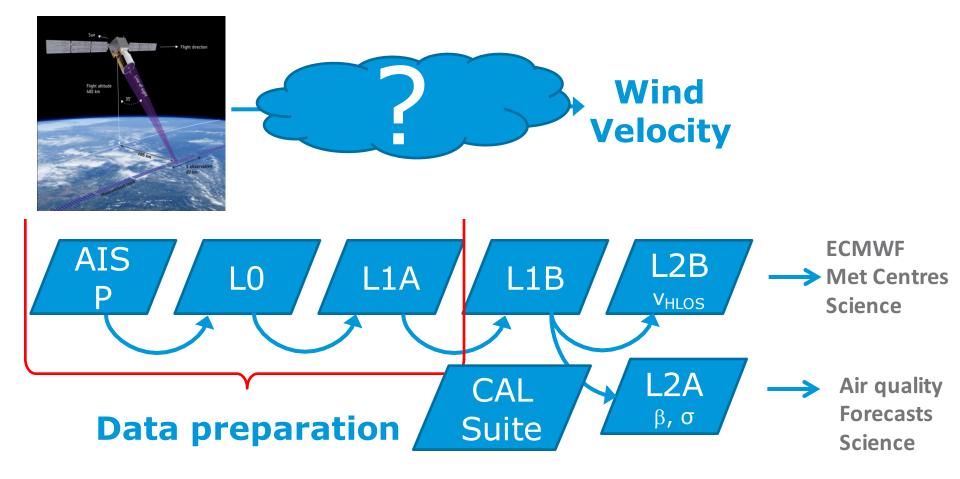
Data processing and distribution





Data Processing





Mission products



1. Primary product (L2b):

Horizontally projected LOS (HLOS) wind profiles

- Approximately zonal at dawn/dusk (6 am/pm)
- ~85 km observation from 3 km subsamples scene classified
- Aeolus L1b product available NRT + L2b processor from ECRWF Data format L1b: ESA EE binary format. L2b BUFR convertor

- Con averages from 3 km subsamples

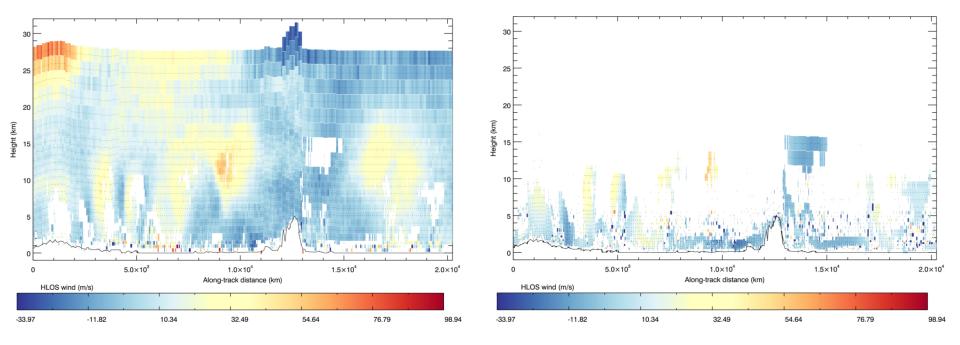
2. Spin-off

- Aeolus L2a product available NRT Aeolus L2a product averages from 3 Cloud/aerosol cover/a: Cloud/aer

 - Cloud/aerosol base height (optically thin)

Simulated Aeolus Rayleigh (left) and Mie (right) winds





Courtesy Michael Rennie, ECMWF

(L2B processor development: KNMI & ECMWF)

Data access portal



	Online Dissemination	European Space Agency
ESA Earthnet		Welcome Guest
		Collections
Directory 1	Tree View - L2B_Products	
L2B_Products		Info
Collection	L2B_Products	
Baseline	2B03	
Year-Month	2007-10	
Day	30	
Available products	s:	
AE_OPER_ALD		
	EO-SIP EO Product Browse Image Metadata	
AE_OPER_ALD	D_U_N_2B_20071030T155029_20071030T172341_0002	

http://aeolus-ref-addf.eo.esa.int/addf/

ADM-Aeolus: Observational Requirements



Requirement			Observation Requirements		
ID			PBL	Troposphere	Stratosphere
MR-85	Vertical Domain	[km]	0-2	2-16	16-20 (30)*
MR-60	Vertical Resolution	[km]	0.5	1.0	2.0
MR-80	Horizontal Domain			Global	
MR-70	Number of Profiles (sampling)	[hour ⁻¹]		>100	
MR-150	Minimum horizontal track data availability	[%]		95	
MR-75	Temporal sampling	[hour]		12	
MR-50	Horizontal observation size	[km]	15	(goal) – 100 (thr	eshold)
MR-50	Horizontal measurement size	[km]		3 km	-
MR-110	Precision (HLOS Component)	[m/s]	1	2.5	3 (3-5)*
MR-100	Systematic error (HLOS component)	[m/s]		0.7	
MR-90&95	Dynamic Range, HLOS	[m/s]		±100 (150)*;	k
MR-120	Error Correlation (per 100 km and between adjacent vertical bins)			< 0.1	
MR-130	Probability of Gross Error	[%]		5	
MR-140	Timeliness	[hour]		3)
MR-160	Length of Observation Dataset	[yr]		3	



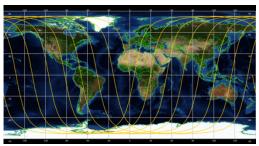


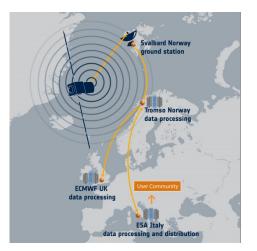
Examples of product error sources

Examples of ADM-Aeolus error sources









1. Instrument errors

- a. Instrument alignment and transmission
- b. Spectrometer imperfections
- c. Instrument degradation and laser stability,

2. Satellite / orbit related errors

- a. Harmonic biases from thermal variability
- b. Range dependent biases
- c. Pointing stability, ...

3. L1 (and lower) processing errors

- a. Calibration
- b. Signal processing and QC
- **c.** EQ, ...

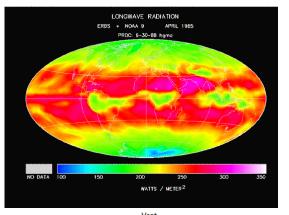
4. L2 processing errors

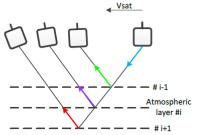
- a. A-priori T and p (ECMWF)
- b. Calibration, signal processing and QC ...
- **c.** EQ, ...

Examples of spatially varying error sources









- **1. Harmonic** variations in instrument alignment over an orbit lead to **wind biases**:
 - a. **Thermo-elastic** effects from changes in the solar aspect angle
 - **b. Thermo-elastic** effects from changes in shortwave and thermal fluxes from Earth
 - c. Satellite altitude varies through orbit (harmonic range-dependent biases)

Bias correction implemented using ground returns and error fitting through harmonic functions

- Satellite movement along circular orbit cause variable backscatter angle on telescope as function of range (time)
 - Range Dependent wind bias correction
 scheme implemented

3. Regional T and p accuracy variations

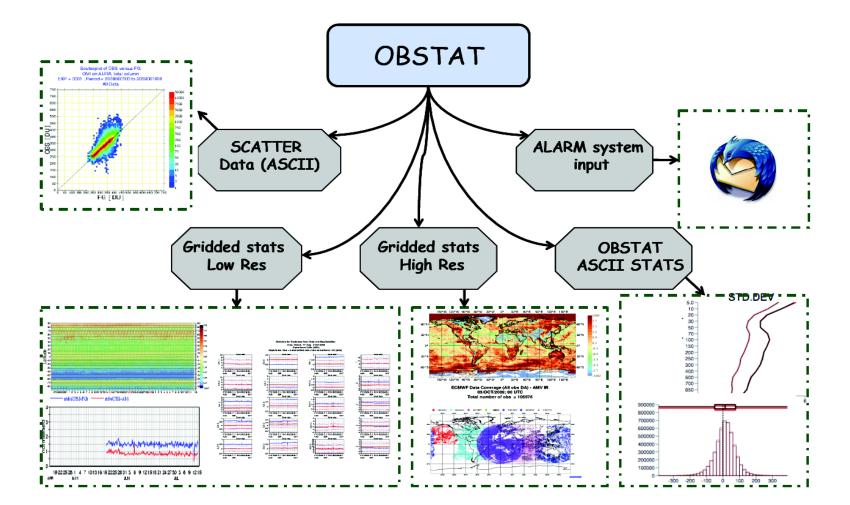
ADM-Aeolus CAL/VAL needs



- 1. Characterization, calibration and validation needed on instrument, satellite and product levels to **verify Mission Requirements**
 - a. Industry, ESA, algorithm core teams, CAL/VAL teams
- 2. Verification and validation needs addressed by **CAL/VAL teams**:
 - a. Verification and validation on **several product levels** (L0, L1b, calibration files, L2a, L2b, L2c) looking at selected scenes
 - b. NWP monitoring (i.e. comp. L2 HLOS and NWP model wind)
 - c. Validation by comparison to **collocated observations** with similar and different instrumentation
 - Airborne (short-term, well collocated), ground-based (long-term, less frequent collocations)
 - **d.** Short and long term calibration and validation (minutes, hours, days, weeks, seasons, lifetime)
 - e. Appropriate geographical coverage
 - f. Comparison with independent retrieval algorithms

Example of planned NWP monitoring of Aeolus at ECMWF (1/2)

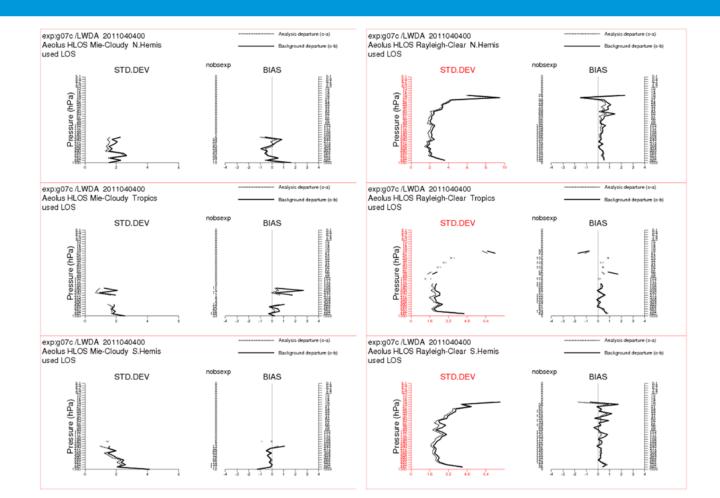




Some examples of OBSTAT output Courtesy Mohamed Dahoui (ECMWF)

Example of planned NWP monitoring of Aeolus at ECMWF (2/2)





Example OBSTAT plots for assimilated Aeolus L2B winds. Mie-cloudy on the left, Rayleigh-clear on the right. Courtesy Mike Rennie (ECMWF)



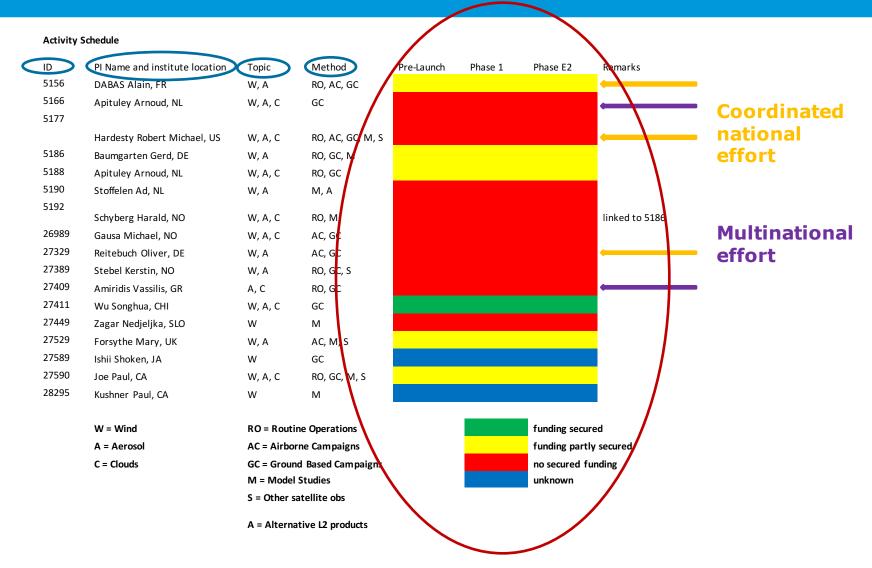


ADM-Aeolus (delta-) AO CAL/VAL Call 2014 -

responses

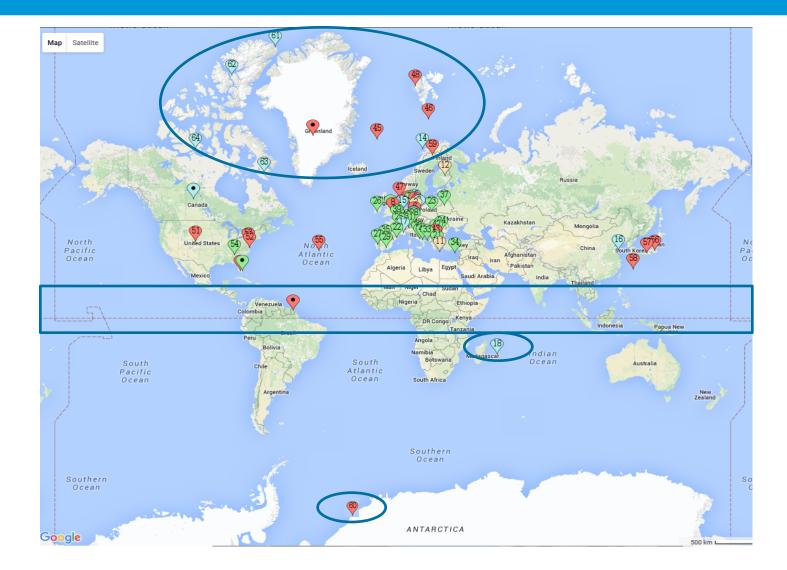
17 ADM-Aeolus CAL/VAL Proposals – all selected after review





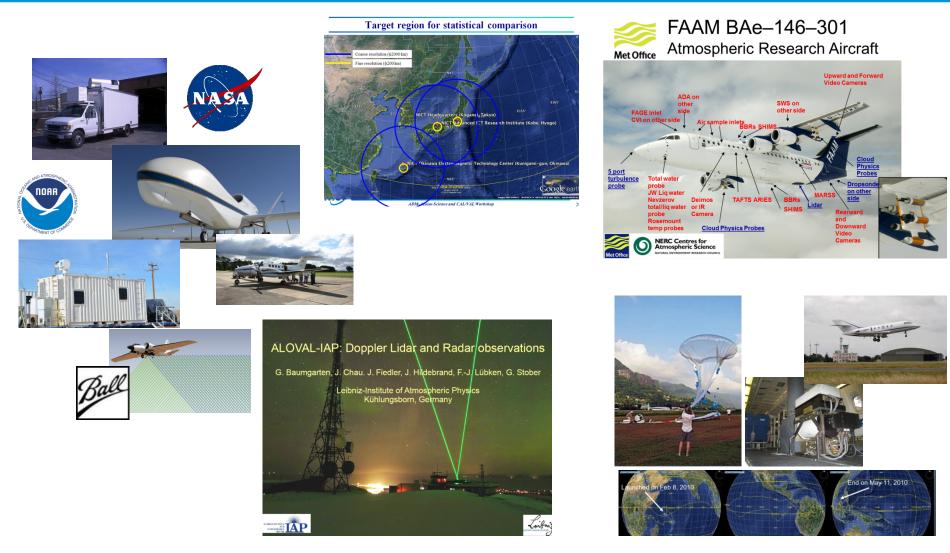
Geographical coverage CAL/VAL proposals





Examples proposed Aeolus CAL/VAL Activities

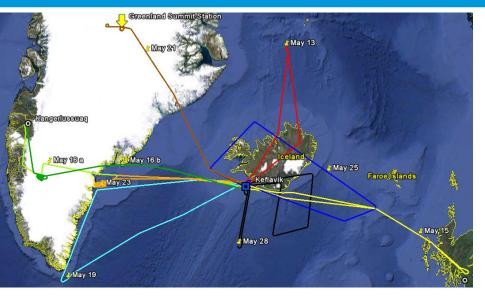


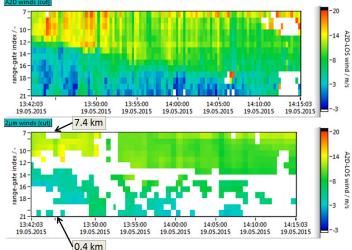


WindVal pre-launch campaign – May 2015

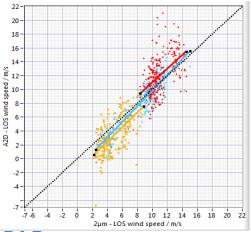








Statistical Resultscorr. coeff. r = 0.89N points= 765slope= 1.28std. dev.= 2.2 m/savg. bias= -0.17m/s



Credits U. Marksteiner, DLR



- 1. ADM-Aeolus Science and CAL/VAL Workshop held in February 2015
 - Instrument, processing, science and CAL/VAL Plans presented
- 2. Draft CAL/VAL Implementation Plan reviewed by PIs and being updated
- 3. CAL/VAL Coordination & Rehearsal Workshop planned for Q1 2017
- 4. ADM-Aeolus launch readiness 4th QRT 2017
- 5. Phase E1 CAL/VAL Workshop at L+3 months
- 6. Regular workshops throughout phase E2

Concluding remarks



- ADM-Aeolus selected in response to identified deficiency in the Global Observing System w.r.t. global coverage of direct wind profile observations
- 2. ADM-Aeolus will serve Numerical Weather Prediction and Air Quality Forecasting and support Climate Modelling (improved parameterization)
- 3. 17 (inter-) national CAL/VAL teams are getting ready to validate and exploit ADM-Aeolus data
- 4. CAL/VAL Implementation Plan drafted and reviewed
 - Coordination and further expansion of activities on-going
 - National funding confirmation sought by end 2016
 - Pre-launch campaigns -> Key for rehearsal and lessons learnt
- 5. ADM-Aeolus launch readiness: 4th quarter 2017
- ADM-Aeolus L1 and L2 data availability to science community expected 3-5 months after launch

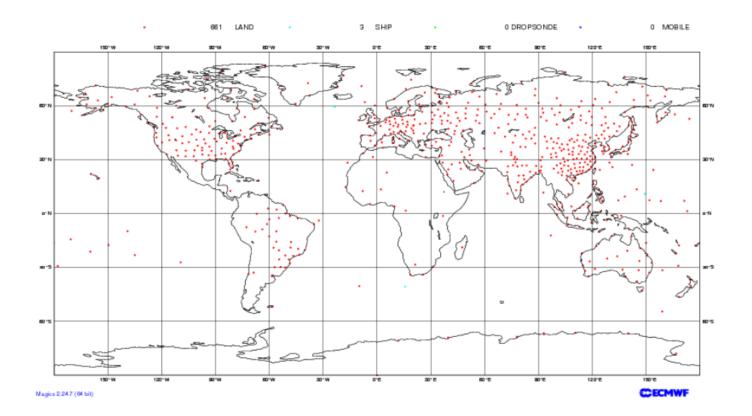


Backup

Radiosonde network



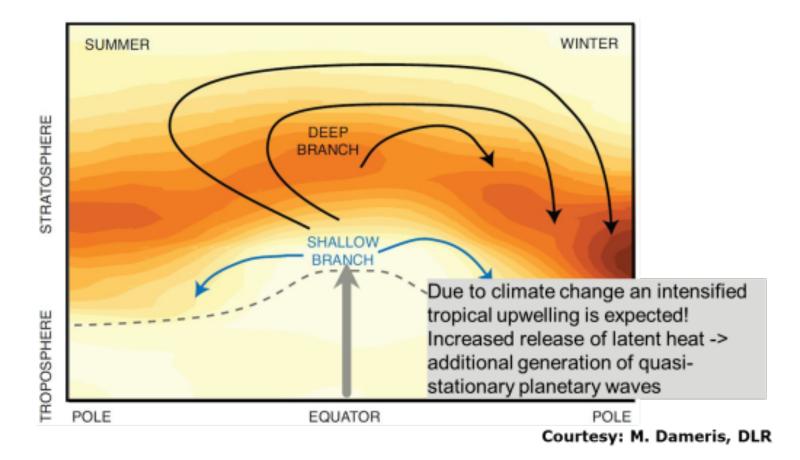
ECMWF Data Coverage (All obs DA) - Temp 10/Feb/2016; 00 UTC Total number of obs = 664



Importance for winds for climate applications

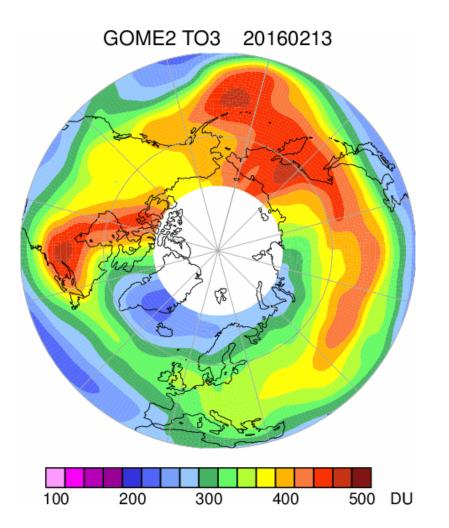


Tropical ozone strongly impacted by UTLS dynamics (e.g. convection, gravity waves, planetary waves)



Ozone hole event NH 2016



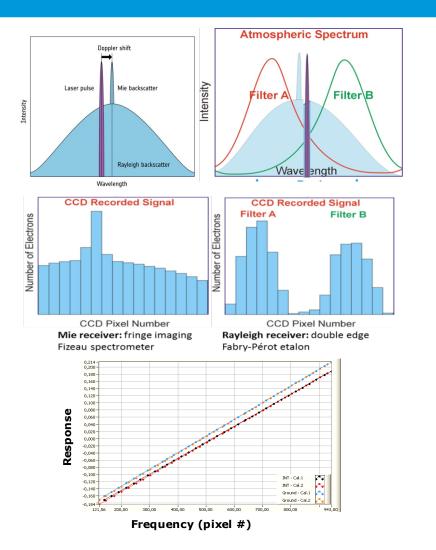


Courtesy, M. Weber, J. Burrows and colleagues, IUP Bremen

WFDOAS Algorithm Weber IUP University Bremen

Examples of time varying error sources





- Regular detector **response**
 calibrations (weekly) to detect and correct short-term instrument
 (alignment) drifts
- 2. Laser emit frequency and pulse energy monitoring
- **3. Seasonal instrument alignment** variability



Temporal coverage CAL/VAL Proposals



- 1. Most proposals foresee CAL/VAL throughout phases E1 and E2
- 2. Most have limited resources, hence campaigns are limited in number and time-span
- 3. Manpower and hardware maintenance for **long-term ground-based monitoring needs attention**
- 4. Iterations with teams to look for **possibilities to expand and coordinate activities**
 - Piggy-backing on campaigns for other missions (e.g. S5p, S1, S2, S3, ...)
 - Year of Polar Prediction (YOPP, 2018 -2019)
 - Tropical campaigns
 - ...

ADM-Aeolus CAL/VAL Implementation Plan



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