Comparing CO2/IRW and H2O/IRW CTPs

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CO2 slicing and H2O intercept techniques are used to assign cloud tracer heights in Atmospheric Motion Vector determinations. Resulting CTHs using GOES-13 data are compared with CALIOP CTHs.
IRW - traditional relation of opaque cloud height and $T(p)$
The CO2/IRW ratio of measured cloud signal yields $P_c$.
Emissivity for ice cloud is similar for 11 and 13.3 um bands.
For a single layer of clouds, radiances in one spectral band vary linearly with those of another as single layer cloud amount varies from one field of view (fov) to another. H2O/IRW technique for inferring CTP of a cloud cluster is based on this.

CTP can be inferred by extrapolating to opaque cloud conditions.
Some Details (1)

- Box size (line X element) used is 5 X 7 (35 observations), roughly [20 Km]**2 box at the GOES-13 Imager satellite subpoint.

- The IRW only algorithm uses measured 11 µm brightness temperature (BT) and an atmospheric profile to determine Cloud Top Pressure (CTP) at each cloudy field of view (FOV). Effective Cloud Amount (ECA) for each cloudy FOV is assumed to be 100%.

- For each FOV CO2 Slicing (CO2/IRW) determines a single CTP and ECA using 13.3 µm and IRW radiances measurements.

- Water Vapor Intercept (H2O/IRW) generates a single CTP for the entire box, where the assumption is that all the cloudy field of views represent a single cloud layer and only the ECA, or thickness, is changing.
Some Details (2)

- The atmospheric first guess is based on hourly interpolated forecasts from the 3 hourly GFS. Horizontal resolution of first guess is 0.50 deg lat/lon, and vertical resolution is 25 hPa from 1000 hPa to 900 hPa and 50 hPa from 900 hPa to 100 hPa.

- The surface analysis (Temperature at Sea Level) is based on hourly surface observations over land and buoy observations over water using the atmospheric guess as a background. Over water (oceans only) a daily Sea Surface Temperature (12 UTC), which is based on NOAA Polar Orbiting observations.
Some Details (3)

• AMVs are generated on an hourly basis using the XX:45 UTC as the processing time. This allows for one hemispheric image every three hours (00, 03, 06, 09, 12, 15, 18, and 21 UTC).

• CO2/IRW and IRW CTPs at full resolution (single FOV) and H2O/IRW at box resolution (5 line X 7 elements) are generated simultaneously.

• The statistics provided in the various figures are based on CO2 and IRW point data and H2O box data.
References


Comparison of IRW and IRW/H2O Cloud Top Pressure to CO2/IRW CTP between 440 and 100 hPa. (Left) Number of occurrences of CO2/IRW CTP's in the indicated ECA intervals. (Right) Average CTP for the three techniques at the varying ECA categories. The x-axis and y-axis are intervals of ECA (%) and Cloud Top Pressure (hPa), respectively.
Comparison of the four GOES Cloud Product algorithms - GOES Imager (CO2/IRW, IRW, and IRW/H2O) and GOES Sounder CO2 Slicing (Cloud Absorption Technique Sounder). This data set is from GOES-13 on 24 June 2011 at 12:00 UTC.
Between 600 hPa and the tropopause from GOES-13 on 24 June 2011 at 12:00 UTC
H2O/IRW vs CO2/IRW Techniques

Color bar represents number density per block.
Comparisons with CALIOP

Cloud-top pressures were converted to heights using the Global Forecast System (GFS) and were compared to heights from analysis of Cloud-Aerosol Lidar with Orthogonal Polarization (CALIOP) 0.532-m backscatter data averaged to 1 km footprints.
532 nm Perpendicular Attenuated Backscatter km\(^{-1}\) sr\(^{-1}\) UTC: 2010-12-14 18:36:14.3 to 2010-12-14 18:49:43.0 Version: 3.01 Nominal Daytime
H20/IRW vs CO2/IRW CTHs

color bar represents number density per block.

For CTHs above 4 km
H20/IRW vs CO2/IRW CTHs

color bar represents number density per block.

For all CTHs
For all CTHs

H2O/IRW vs IRW CTHs

color bar represents number density per block.
For all CTHs

IRW vs CO2/IRW CTHs

color bar represents number density per block.
Algorithm comparisons

IRW

H2O

CO2

H2O

IRW

H2O

CO2

IRW
ABI algorithm

Stats: Count, Accuracy, Precision (km)

All Stats: 1396 / -1.144 / 3.404

Ice Stats: 517 / -0.925 / 3.041

Water Stats: 307 / -1.511 / 3.917

Phase P.O.D.: 0.93  Mask P.O.D.: 0.94

Act. Cld Frac: 0.61  Pass. Cld Frac: 0.63
Schreiner algorithms
goes13_2010_348_1845 DES NODE

- Stats: Count, Accuracy, Precision (km)
  - All Stats: 1396 / -2.336 / 2.705
  - Ice Stats: 460 / -2.602 / 2.280
  - Water Stats: 28 / 2.048 / 4.745
- Phase P.O.D.: 0.93  Mask P.O.D.: 0.94
- Act. Cld Frac: 0.61  Pass. Cld Frac: 0.63
Conclusions

* H2O/IRW & CO2/IRW CTP determinations show modest correlation for AMV cloud tracers above 4 km
* H2O/IRW CTH estimates are about 1 km lower than CO2/IRW on average, for semi-transparent ice clouds this increases to 4 km
* CALIOP offers excellent opportunity for cal/val
* GOES-13 CO2/IRW CTH estimates are in better agreement with CALIOP
* ABI AMV CTH estimates are anticipated to be of better quality (better spatial resolution, spectral characterization, and radiometric calibration) with improved AMV tracer characterization (cloud phase, thickness, microphysics, …).