

#### Derivation of AMVs from single-level retrieved MTG-IRS moisture fields

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- Motivation and methodology
- Single-level MTG-IRS humidity retrievals
- Feature tracking algorithm and comparison metrics
- Feature tracking using:
  - Model fields
  - Retrieval fields
  - Smoothed retrieval fields



### Feature tracking on model levels

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#### **Motivation**

- MTG-IRS data will provide accurate and highresolution humidity retrievals: ~1km vertical, 4km horizontal, and 30 minute temporal
- Feature tracking at model levels avoids explicit height assignment
- Removes explicit error contribution

#### Methodology

- Use Met Office UKV 1.5km model to generate simulated spectra
- Use NWPSAF 1DVar retrieval to generate single-level humidity fields
- Use feature tracking code to generate AMVs for comparison with true model winds



### MTG-IRS humidity retrievals

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**Retrieval of fine scale** structure using obs at MTG-IRS resolution



#### Background







### Feature tracking algorithm

- Modified CPTEC tracking software ٠
- Time interval between images = 30 minutes
- Target window size = 6x6, 8x8, 10x10, 12x12
- Euclidean distance technique used for target matching
- Correlation and contrast check, plus AQC scheme





Image 2



#### **Comparison metrics**

Simulation study allows for direct comparison with UKV model winds

$$MSB = \frac{1}{N} \left( \sqrt{u_T^2 + v_T^2} - \sqrt{u_D^2 + v_D^2} \right) \equiv \frac{1}{N} \left( V_T - V_D \right)$$

$$MMVD = \frac{1}{N} \sqrt{V_T^2 + V_D^2 - 2V_T V_D \cos\left|\theta_T - \theta_D\right|}$$

where  $u_T$ ,  $v_T$ ,  $V_T$ ,  $\theta_T$  relate to the true winds  $u_D$ ,  $v_D$ ,  $V_D$ ,  $\theta_D$  relate to the derived winds



#### Good representation of true wind field



### Tracking model fields @ 795hPa

Truth tracked winds d=6

Truth tracked winds d=10

Model wind field

(winds slower than 2.5m/s not seen)

0-2.5m/s	No barb
2.5m/s	Short barb
5m/s	Long barb



Fewer (and slower) winds at lower levels



#### Tracking model fields: MSB and MMVD





### Tracking retrieval fields @ 656hPa

Retrieval tracked winds d=6 Model tracked winds d=6 Model wind field 53 52 51 50  $^{-2}$ 0 2 -4 4 1000 2000 3000 4000 5000 humidity [ppa]

Humidity field at 09:30 [ppa]

#### Much fewer winds!

0-2.5m/sNo barb2.5m/sShort barb5m/sLong barb



### Tracking retrieval fields @ 656hPa

Retrieval tracked winds d=10 Truth tracked winds d=10

Model wind field

0-2.5m/s No barb

Short barb

Long barb

2.5m/s

5m/s



Humidity field at 09:30 [ppa]

#### Much fewer winds!



### Are the humidity retrievals too noisy?

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#### Gaussian multi-scale representation

- Smoothing technique
- Convolution of the image with a 2D Gaussian kernel G(x,y)
- $\sigma^2$ dictates the spread of the Gaussian function and hence the level of smoothing/range of frequencies removed
- Choose  $\sigma^2$  such that the noise is reduced without smoothing away fine-scale features and strong gradients





# Truth tracked vs smoothed retrieval tracked winds

Truth tracked winds d=10 (#winds = 22)

Smoothed retrieval tracked winds d=10 (#winds = 17)

Model wind field

0-2.5m/s	No barb
2.5m/s	Short barb
5m/s	Long barb







#### MMVD for smoothed retrievals



Summary Met Office

- Feature tracking in model humidity fields provides a good representation of the true wind field
  - Best results in mid-troposphere comparable MMVD and MSB
- Tracking retrieval fields provides useful wind information but the quantity and distribution of the derived winds is significantly reduced relative to tracking model fields
  - Retrieval fields too noisy
  - Good quality but fewer AMVs
- Gaussian smoothing can eliminate the noise from the retrievals
  but still retain much of the trackable structure
  - Need to reduce the contrast check -> larger MMVD
  - Increased number of AMVs
  - sigma between [1,2] gives the best results



#### Kia ora! Questions and answers



## Tracking model fields @ 521hPa

-2 -4 humidity [ppa]