

## EXPLORING THE BEHAVIOR OF ATMOSPHERIC MOTION VECTOR (AMV) ERRORS THROUGH SIMULATION STUDIES

## Steve Wanzong and Chris Velden

University of Wisconsin - Madison Cooperative Institute for Meteorological Satellite Studies

With contributions from Allen Huang, Mat Gunshor, Jason Otkin, Tom Greenwald Jamie Daniels (NOAA/NESDIS) Wayne Bresky (IM Systems Group, Inc.)

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# **Study Content**

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- Simulated ABI AMVs
- Analysis Strategy (Imposed Noise Effects)
- Comparison to WRF Model Wind Fields
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## **Study Motivation**

GOES-R Advanced Baseline Imager (ABI) -- Expected Launch in ~2017What effect would imposed noise at spec, and over-spec, have on the<br/>derived AMV product?ABICurrent GOES Imager

**Spectral coverage** 16 bands 5 bands **Spatial resolution** 0.64 µm Visible 0.5 km Approx. 1 km Other Visible/near-IR 1.0 km n/a Approx. 4 km Bands (>2  $\mu$ m) 2 km **Spatial coverage** Full disk 4 per hour Scheduled (3 hrly) CONUS 12 per hour ~4 per hour Mesoscale Every 30 sec n/a

Yes

Visible (reflective bands) On-orbit calibration

No





## **ABI Simulations - Methodology**

- Employ the high resolution Weather Research and Forecasting (WRF) mesoscale model to generate simulated atmospheres.
- Calculate Top of Atmosphere (TOA) infrared radiances from the WRF model simulations using CRTM and SOI for ABI bands 7-16 (LW Infrared).
- Calculate TOA reflectances from the WRF model simulations using CRTM and SOI for ABI bands 1-6 (Visible/near-Infrared bands).
- Use automated feature-tracking software to derive AMVs from the simulated fields.

#### **ABI bands via WRF simulation**



ABI band data for 2005 June 04 22:00 UTC

# **GOES-R ABI – CONUS Coverage**

#### Simulated GOES-R ABI



Band 14: 11.2 µm

#### Simulated GOES-R ABI



Band 08: 6.19 µm

#### **GOES-12 Imager**



Band 04: 10.7 µm

#### **GOES-12 Imager**



Band 03: 6.5 µm



## Simulated AMVs: Retrieval and Analysis Strategy

- 1. Obtain a set of 3 precisely calibrated, navigated and coregistered simulated images from the WRF model output for selected spectral channels ("pure" dataset = baseline "truth")
- 2. Employ the CIMSS/NESDIS automated AMV derivation algorithm to target, height assign, track, and QC AMV fields from these simulated images
- 3. Redo 1) above, except with introduced noise effects that represent proposed GOES-R satellite specs, and 3X specs. The noise includes striping, calibration and navigation offsets
- 4. Redo 2) above for each imposed noise AMV sample
- 5. Perform a quantitative error analysis on the resultant AMV fields using an objective toolkit called GRAFIIR, to deduce the effects of the imposed instrument noise on the derived AMV products.



# Imposed ABI Navigation Error -Methodology

- The GOES-R PORD specification for navigation error is +/- 21 microradians (0.75 km).
- Each pixel is given a random compass direction and a random normally distributed (about 0) shift the equivalent of 21 microradians.
- New pixel positions are generated using the random shift and random direction.
- The radiances are then linearly interpolated to these new positions from the original pixel locations.
- Second experiment: 3X Spec



## **GOES-R ABI – NavError (3Xspec)**

#### IR-W AMVs - 5 minute time step



Yellow AMVs – "truth" Blue AMVs -- NavError3x



## **Simulated AMV Analysis Tool**

**<u>GOES-R</u>** <u>A</u>nalysis <u>F</u>acility for <u>Instrument Impacts</u> on <u>R</u>equirements





## GOES-R ABI Simulated AMV Comparison Metrics

All AMVs are QI>80, and compared against WRF model winds

$$MVD = \frac{1}{N} \sum_{i=1}^{N} (VD_i)$$

$$SD = \sqrt{\frac{1}{N} \sum_{i=1}^{N} ((VD_i) - (MVD))^2}$$

Where:

$$(VD)_i = \sqrt{(U_i - U_r)^2 + (V_i - V_r)^2}$$

 $U_i$  and  $V_i \rightarrow AMV$  $U_r$  and  $V_r \rightarrow "Truth"$ 

## **GOES-R ABI - Comparison Statistics** AMVs Derived from ABI Simulated Imagery vs. WRF Model Winds

CIMSS



## **GOES-R ABI - Comparison Statistics** AMVs derived from ABI Simulated Imagery vs. WRF Model Winds

CIMSS





## Imposed ABI Striping Error -Methodology

- The GOES-R PORD spec for striping error is that it should be less than the spec instrument noise.
- Assume a detector array (100 high) has 1 line simulated to be "bad".
- Every 100<sup>th</sup> line has striping error applied by adding a radiance offset equal to the spec noise.
- Second experiment with 3X spec.

## GOES-R ABI – Striping3x

Temperature difference between "truth" and 3x Striping Green is zero difference. Blue stripes are only observed difference.





## **GOES-R ABI – Striping3x**

15 minute time step

Clear sky water vapor tracking





Baseline (no striping) AMVs Band 08 (6.19 µm) Striping3x Band 08 AMVs



## **GOES-R ABI – Striping3x**

15 minute time step

Clear sky water vapor tracking





Baseline (no striping) AMVs Band 08 (6.19 µm) Striping3x Band 08 AMVs White areas -- tracking striping

## **GOES-R ABI - Comparison Statistics** AMVs derived from ABI Simulated Imagery vs. WRF Model Winds

CIMSS



## **GOES-R ABI - Comparison Statistics** AMVs derived from ABI Simulated Imagery vs. WRF Model Winds

сімзз











## **Simulated Katrina**



# 15-Minute Time Step15x15 Target Box Size2 km Resolution

5-Minute Time Step15x15 Target Box Size2 km Resolution





## **Simulated Katrina**



# 15-Minute Time Step15x15 Target Box Size4 km Resolution

15-Minute Time Step15x15 Target Box Size2 km Resolution





## Summary

- Simulated ABI data produced from WRF model TOA radiances is an effective way to study the potential effects of various 'noise' sources and processing choices on AMVs.
- Unaltered radiance fields were used as the baseline ("truth") AMV product.
- Imposed navigation/registration errors have the greatest negative impact on IR and Visible AMVs compared to baseline.
- Striping effects are troublesome for clear sky water vapor AMVs.
- The above findings are effectively quantified using the GRAFIIR data analysis tool.

## **Thank You**





Backups