



2018 CGMS ICWG-2 Workshop
Agency reports:
Japan Meteorological Agency (JMA)

Haruma Ishida*, Kouki Mouri, Hiroshi Suzue, Ryo Yoshida,
Masahiro Hayashi

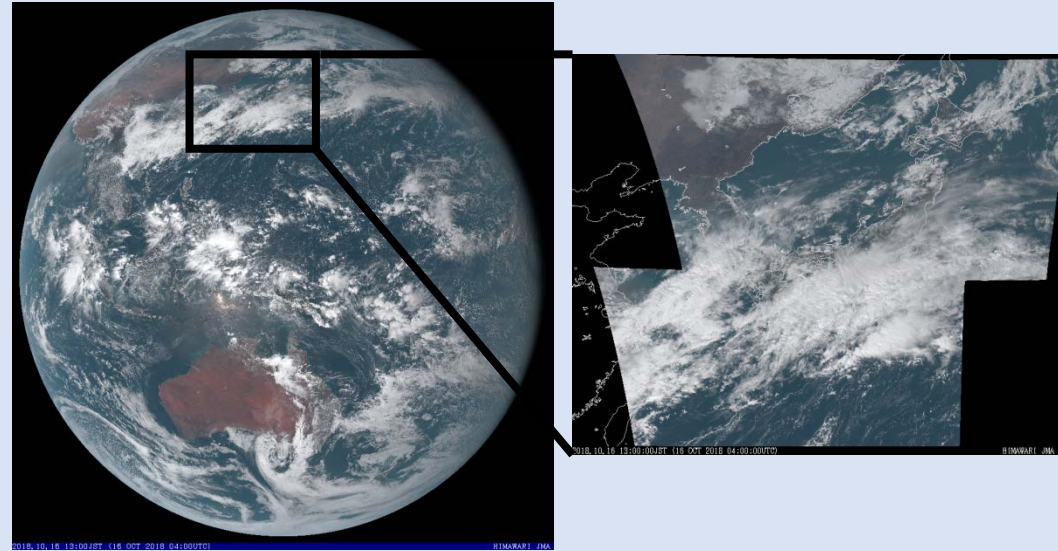
Meteorological Satellite Center (MSC), JMA

1. Spec. of Himawari-8 Advanced Himawari Imager

No.	Wavelength(μm)	Resolution
1	0.47	1 km
2	0.51	
3	0.64	0.5 km
4	0.86	1 km
5	1.6	2 km
6	2.3	
7	3.9	
8	6.2	
9	6.9	
10	7.3	
11	8.6	
12	9.6	
13	10.4	
14	11.2	
15	12.4	
16	13.3	

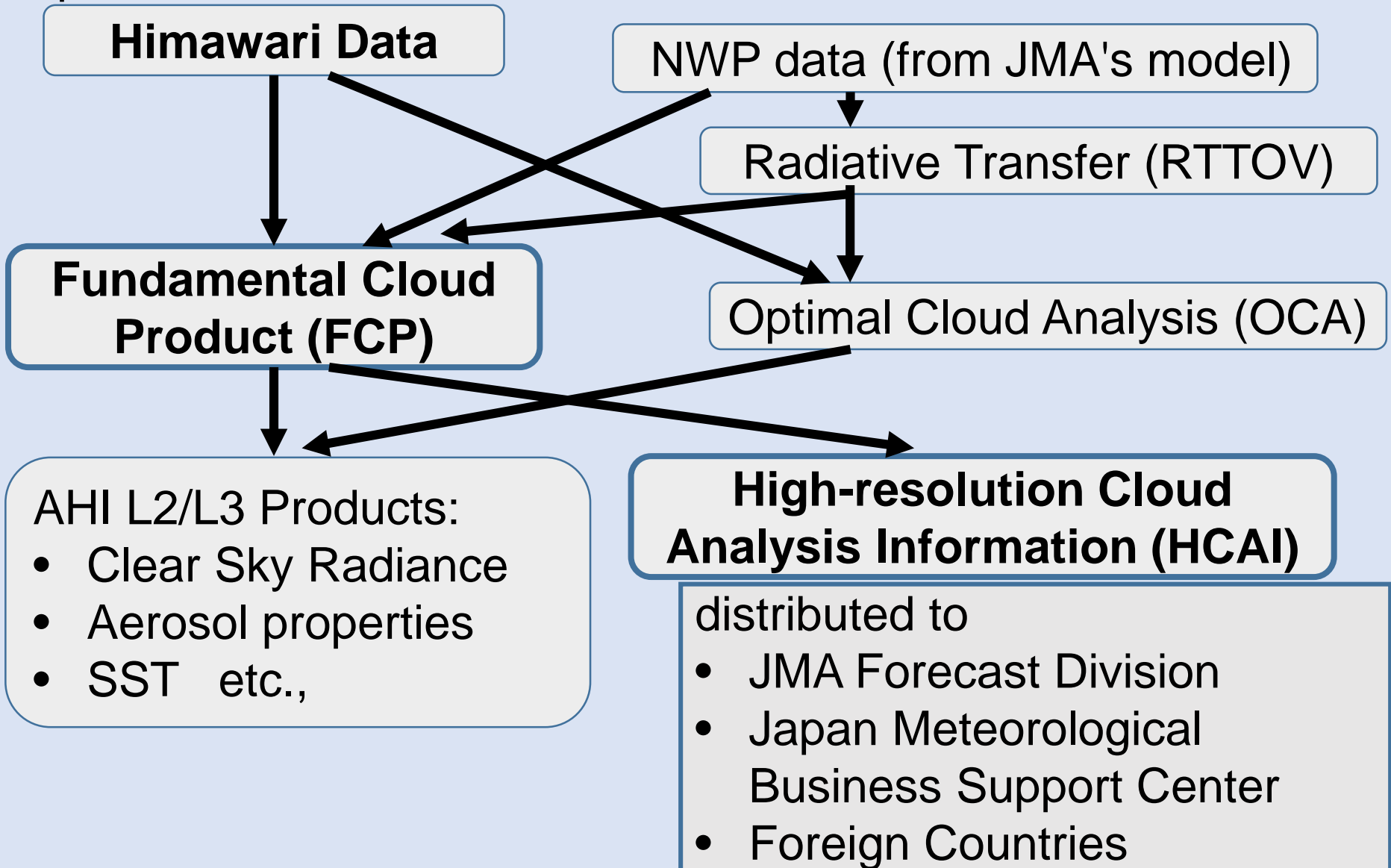
Temporal resolution:

- Full disk: 10 min.
- Japan and mobile obs.: 2.5 min.



2. Himawari Cloud Products

Operation flow:

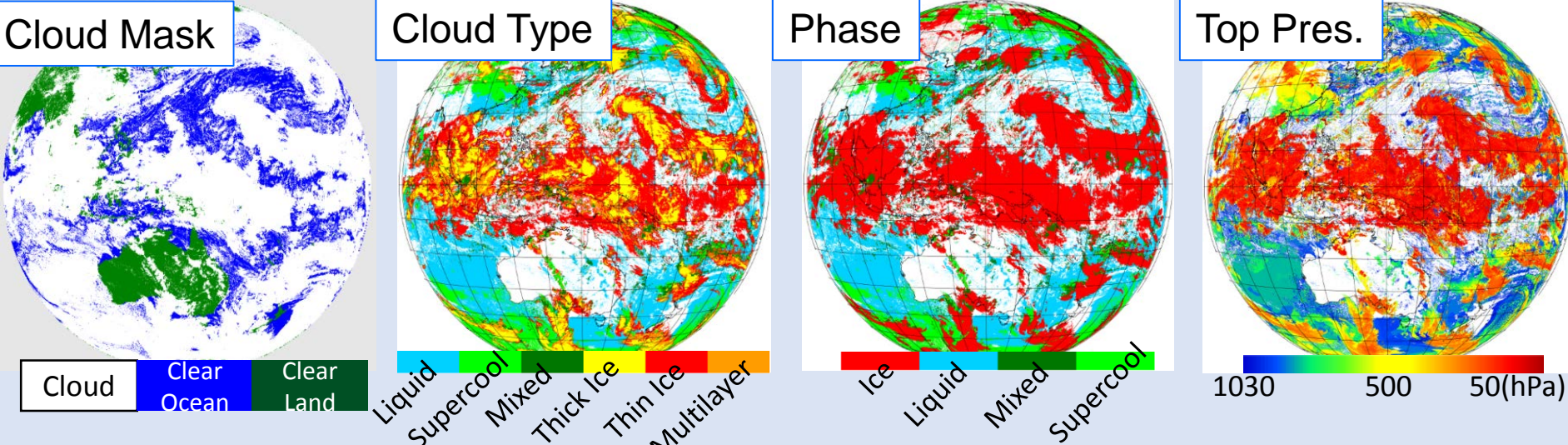


For forecast, disaster mitigation, monitoring, business...

2. Himawari Cloud Products

Fundamental Cloud Product (FCP)

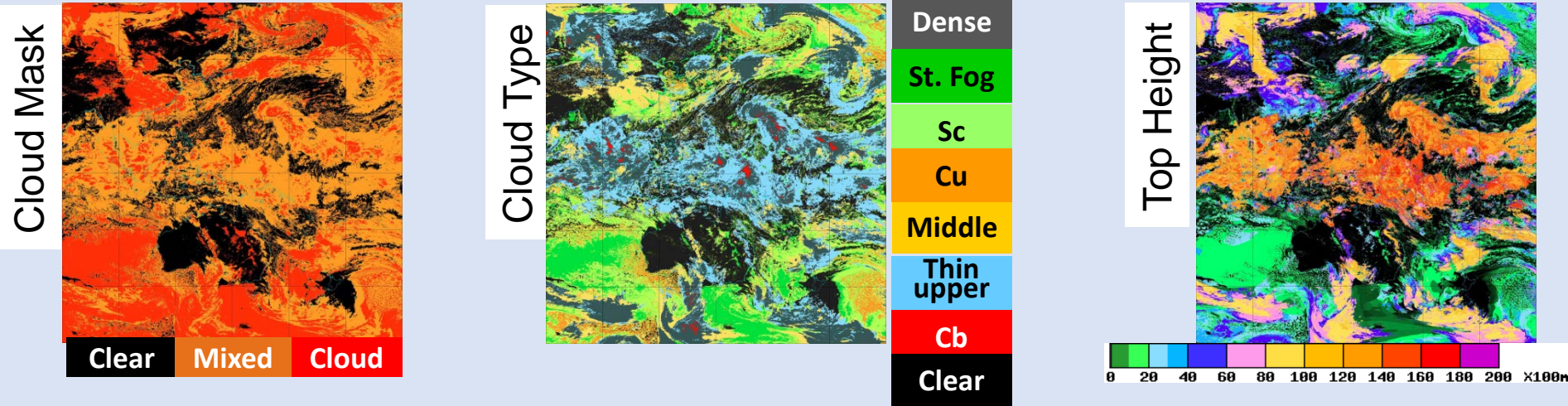
Spatial: same as IR band (i.e., 2 km), Temporal: 1 hour



High-resolution Cloud Analysis of Imager Data (HCAI)

Spatial: 0.02 X 0.02 deg., Temporal: 1 hour

More detailed

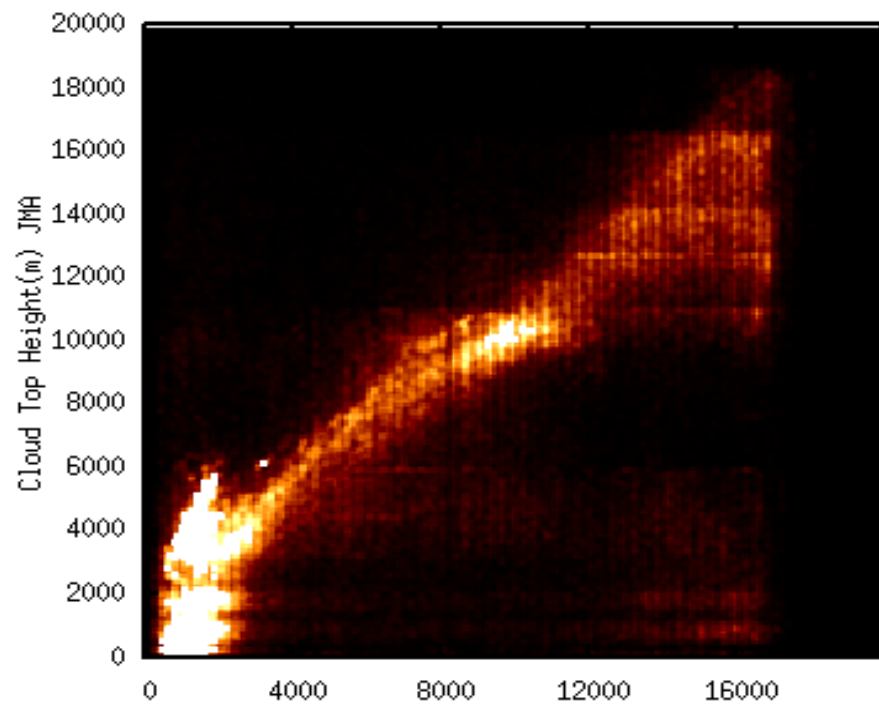


3. Recent improvements

Update Cloud Top Height algorithm

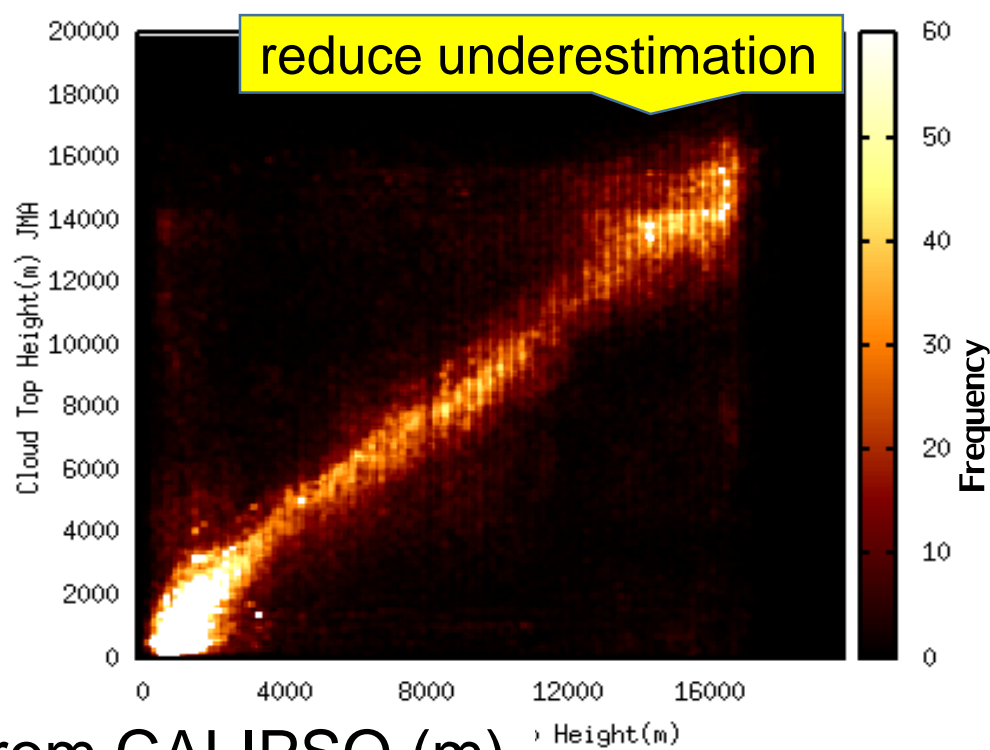
- since 0200 UTC on 21 March 2017
- To correct top height underestimation for optically thin clouds

Previous



New

Sep. 2016, full-disk area



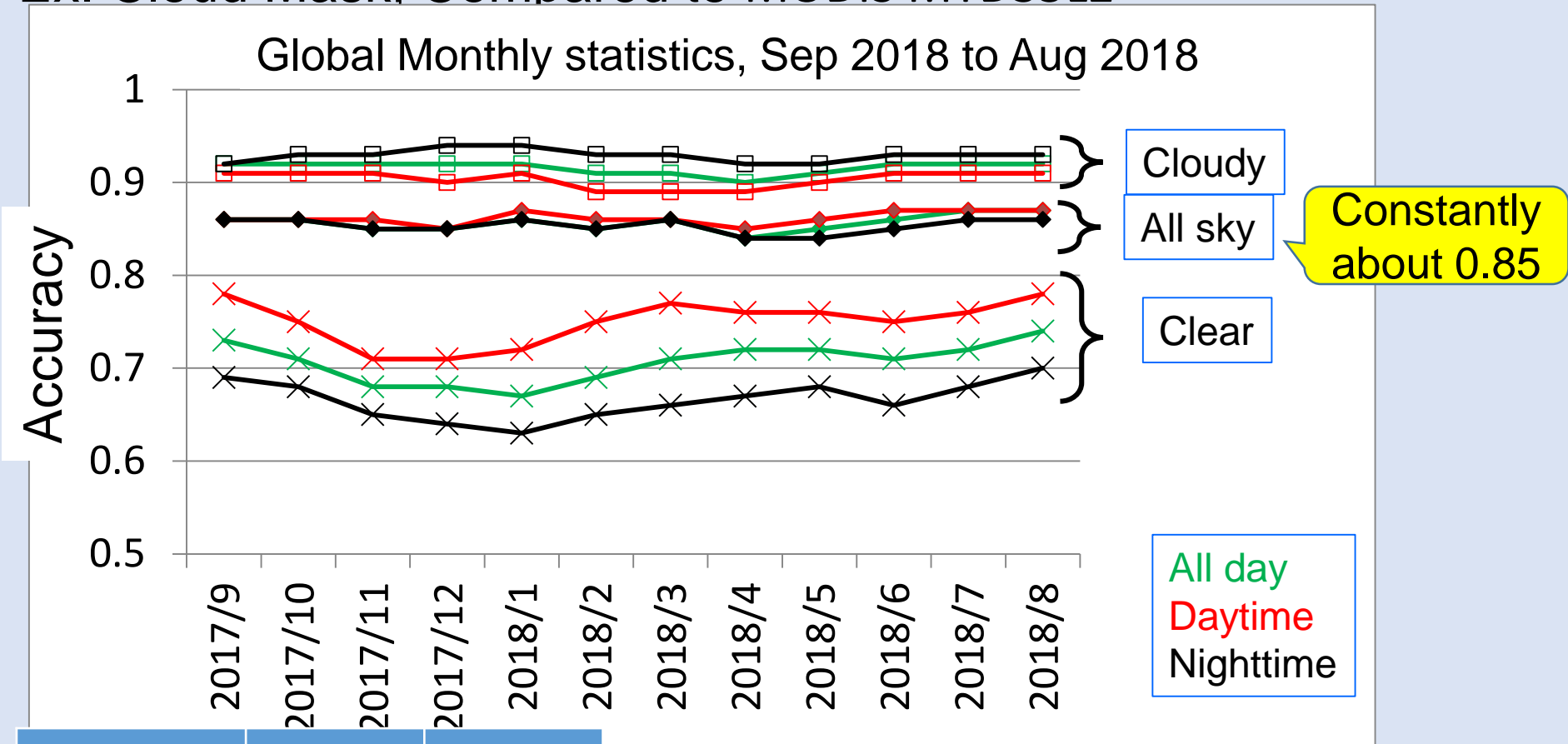
Cloud top height from CALIPSO (m)

Explanation: tomorrow presentation

4. Validation works

Products are routinely validated.

Ex. Cloud Mask; Compared to MODIS MYD35L2



	MODIS Clear	MODIS Cloud
JMA Clear	A	B

$$\text{All sky accuracy} = \frac{A + D}{A + B + C + D}$$

Checking the accuracy and its fluctuation

5. Future Plan

Improvement of current cloud products:

- 10-minute interval production
 - ✓ To speed up the running

Himawari-8 new products under construction:

- Fog monitoring (land and ocean, day and night)
- Snow/Ice surface detection
- Surface solar radiation
- Sunshine duration

Improvement of operational cloud products by Meteorological Satellite Center of Japan Meteorological Agency



Haruma Ishida*, Kouki Mouri, Hiroshi Suzue, Ryo Yoshida,
Masahiro Hayashi

Meteorological Satellite Center (MSC), Japan Meteorological
Agency (JMA)

2018 Oct.

1. Introduction

Two topics:

1. Improvement of cloud top height in operational cloud products of Advanced Himawari Imager (AHI) by JMA/MSC
 - ✓ Point of algorithm change
 - ✓ Validation
2. Investigation of the applicability and utility of machine-learning techniques for cloud product algorithm
 - ✓ especially cloud mask and type discrimination
 - ✓ A preliminary study for future operation

2. Improvement of Cloud top height

2-1. New Algorithm

Change from single cloud layer model to double layer

In the optimal estimation method:

T_{c1}	$BT(11.2\mu\text{m})$
$\varepsilon_{c1}(11.2\mu\text{m})$	$BT(11.2) - BT(12.4)$
$\beta_{c1}(12.4, 11.2)$	$BT(11.2) - BT(13.3)$
T_{c2}	$BT(11.2) - BT(8.6)$
$\varepsilon_{c2}(11.2\mu\text{m})$	$BT(6.2\mu\text{m})$
$\beta_{c2}(12.4, 11.2)$	$BT(7.3\mu\text{m})$

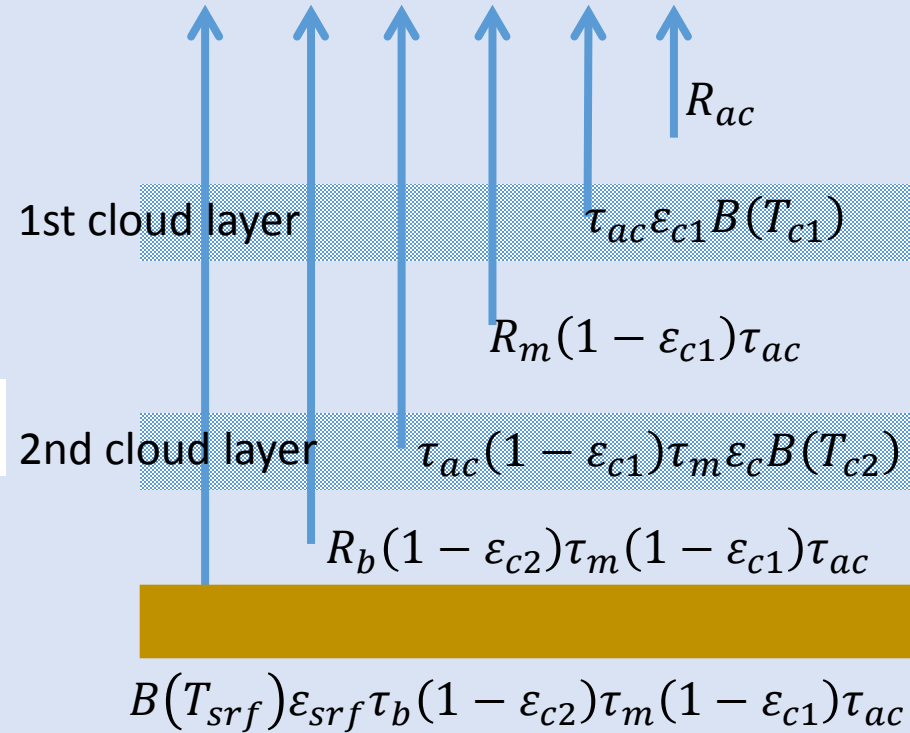
State vector

Dependent vector

T_c ; cloud temp.[K]

ε_c ; cloud emissivity [-]

β_c ; ratio of cloud trans.



Radiative transfer equation for Jacobian calculation:

$$\begin{aligned}
 R_{obs} &= R_{ac} + \tau_{ac}\varepsilon_{c1}B(T_{c1}) + \tau_{ac}(1 - \varepsilon_{c1})R_m + \tau_{ac}(1 - \varepsilon_{c1})\tau_m\varepsilon_{c2}B(T_{c2}) \\
 &+ \tau_{ac}(1 - \varepsilon_{c1})\tau_m(1 - \varepsilon_{c2})R_b + \tau_{ac}(1 - \varepsilon_{c1})\tau_m(1 - \varepsilon_{c2})\tau_b\varepsilon_{srf}B(T_{srf})
 \end{aligned}$$

Cloud top height and pressure derived from temperature

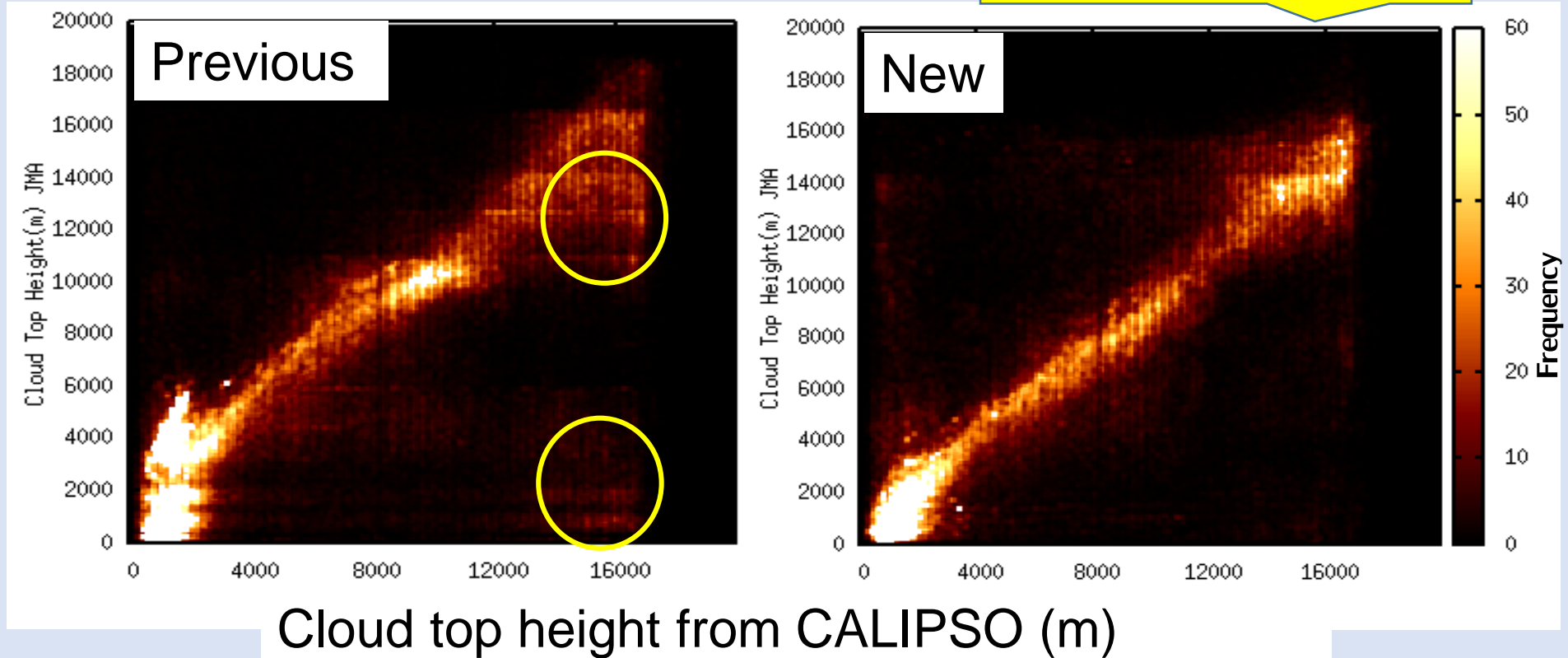
2. Improvement of Cloud top height

2-2. Results

Comparison to CALIPSO:

Sep. 2016, full-disk area

reduce underestimation

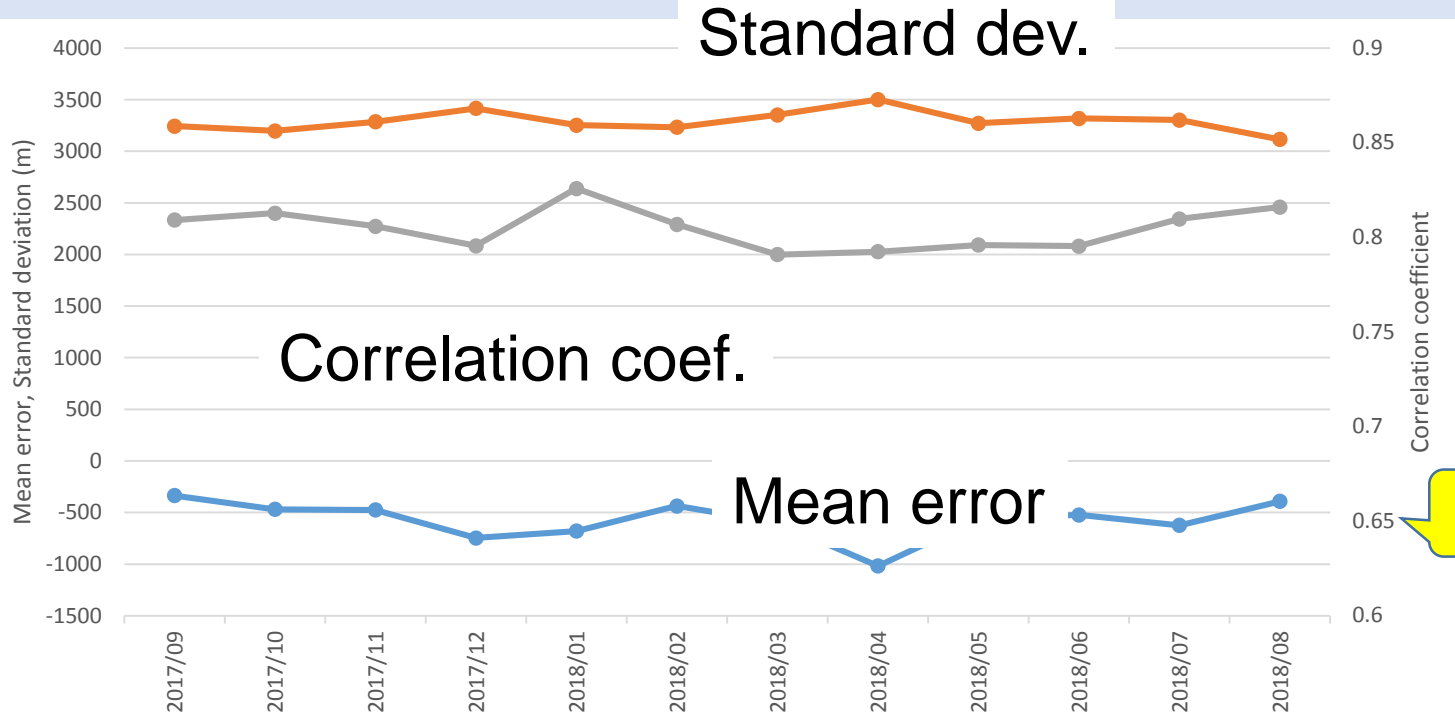


Underestimation reduced

2. Improvement of Cloud top height

2-3. Validation

Global monthly statistics:



yearly	Mean Error [m] Himawari8-CALIPSO	Std. Dev. [m]	Correlation Coef.
Old	-1001.4	3703.8	0.75
New	-490.6	3148.9	0.82

Improved, but the difference from CALIPSO still remains

3. Applicability of machine-learning

3-1. Difficulties of cloud (type) discrimination

Cloud (type) discrimination involves own inherent difficulties:

- “subjectivity” of cloud (type)
 - ◆ Cloud properties **continuously** varies
 - ◆ the boundary among them (e.g., clear/cloudy) intrinsically **vague**
 - The cloud (type) definition (i.e., the criteria of “correct”): determined subjectively depending on purposes
 - **No** absolutely correct criteria of cloud (type)
- Incorrect discrimination: unavoidable
 - ◆ A variety of conditions: difficult to consider all situations in advance of constructing a **classifier** (e.g., rare or local cases)
 - A classifier adjustment --- new incorrect results under other conditions!
 - Trial and error --- a haphazard way

A difference from other general classification problems

3. Applicability of machine-learning

3-2. Requirements for cloud discrimination methods

Clarify requirements to overcome the difficulties:

1. Procedure of appropriate training dataset preparation
 - ◆ No objectively labeled data
 - To avoid a circular argument
2. To determine a reasonable classifier for each purpose
 - ◆ No absolutely correct criteria, i.e., subjectivity
3. To quantitatively estimate likelihood of cloud type
 - ◆ To treat the vagueness
4. To construct a practical adjustment procedure
 - ◆ to avoid the haphazard way

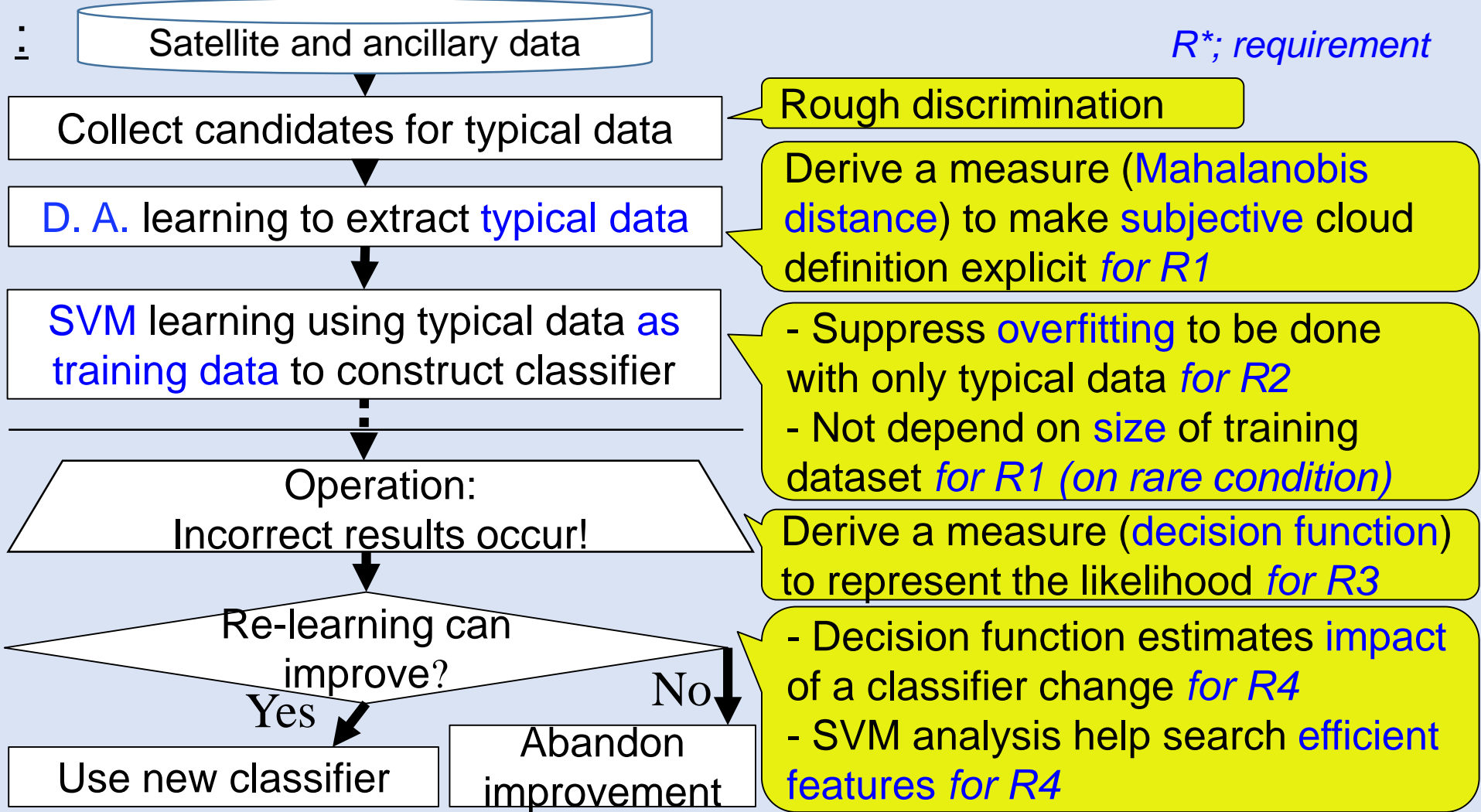
Besides,

- Save computer resource
- The generality to be applicable to various sensors/targets

Machine-learning incorporation: satisfying these requirements

3. Applicability of machine-learning

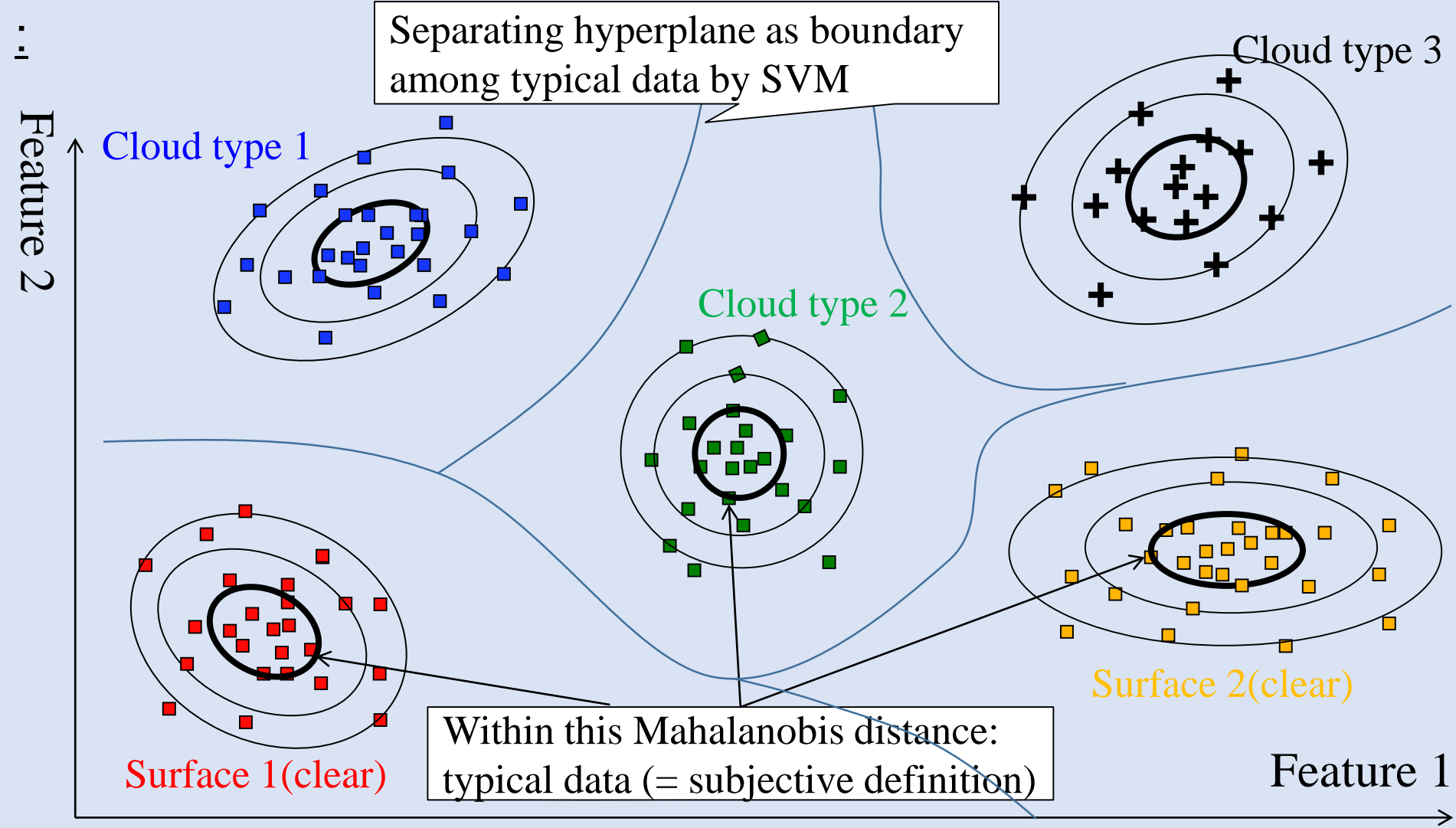
3-3. Development: Flow of method



Ishida et al., 2018, Development of a support vector machine based cloud detection method for MODIS with the adjustability to various conditions. *Rem. Sens. Environ.*, 205, 390–407.

3. Applicability of machine-learning

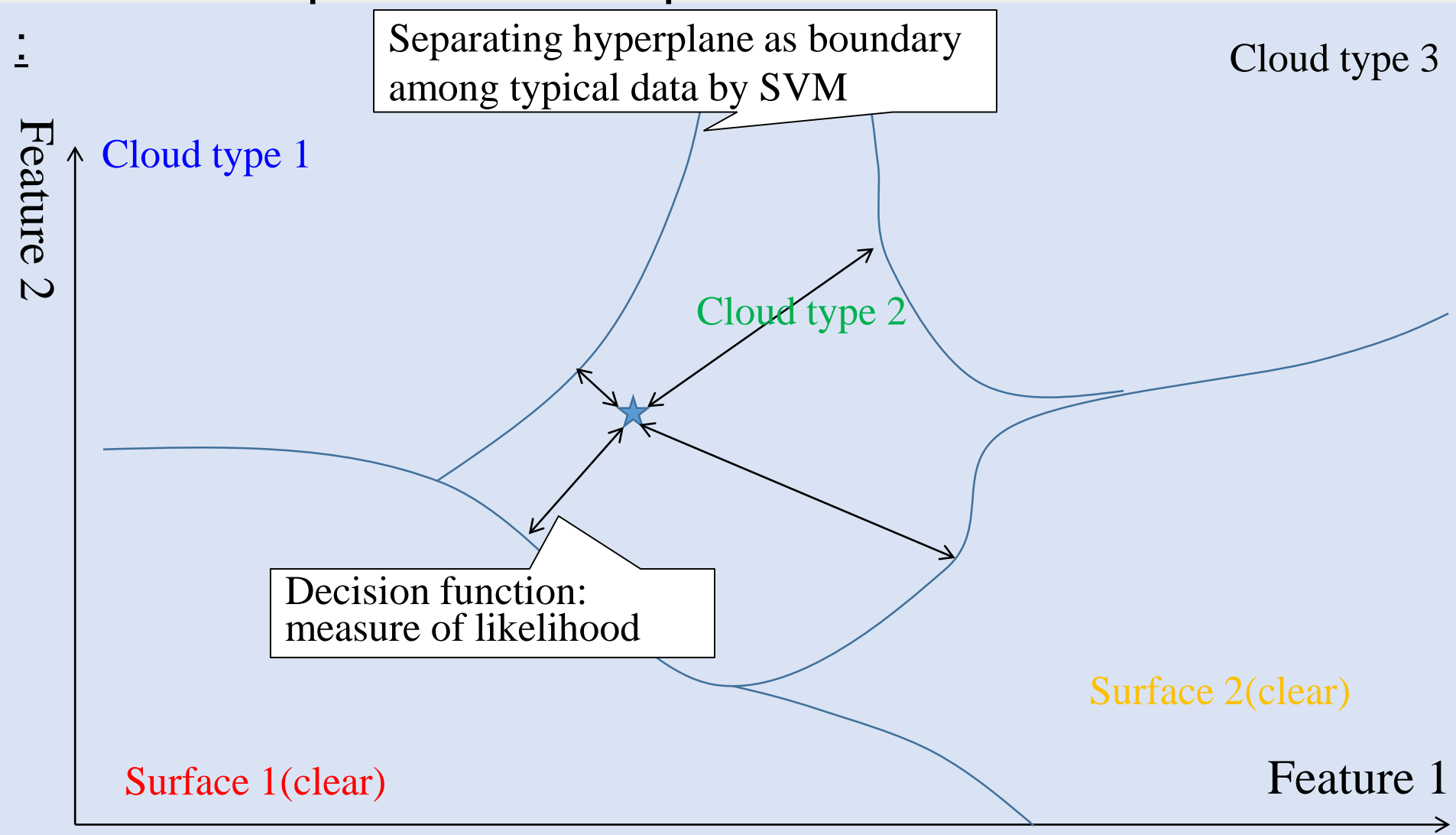
3-4. Development: Conceptual schematic



SVM learning with only typical data; reasonable classifier

3. Applicability of machine-learning

3-4. Development: Conceptual schematic

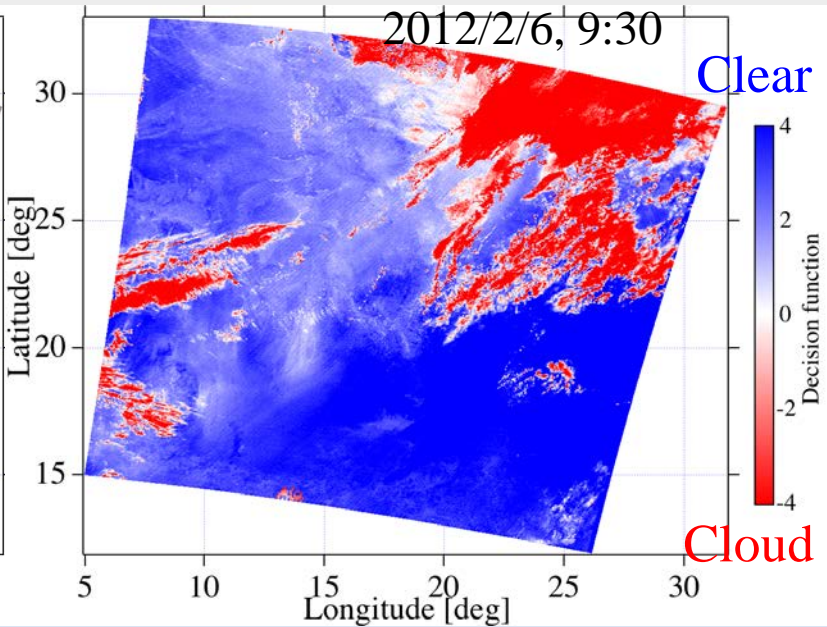
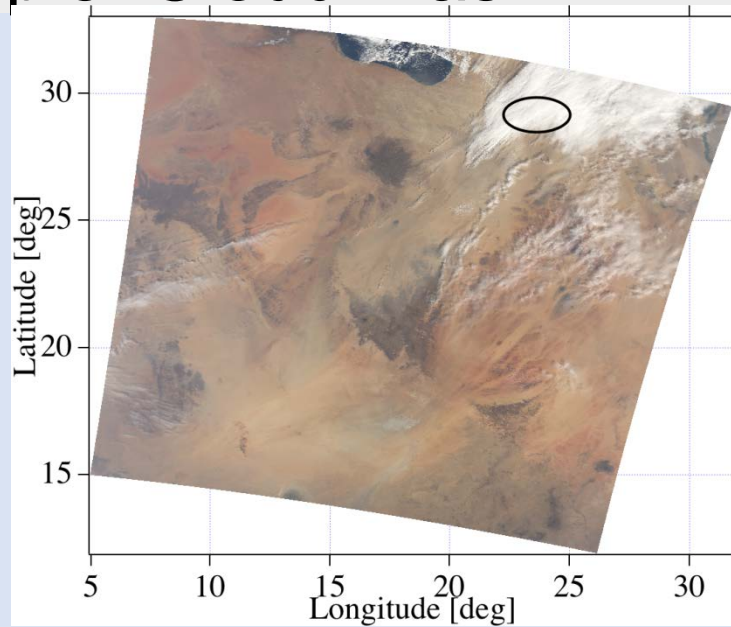


SVM learning with only typical data; reasonable classifier

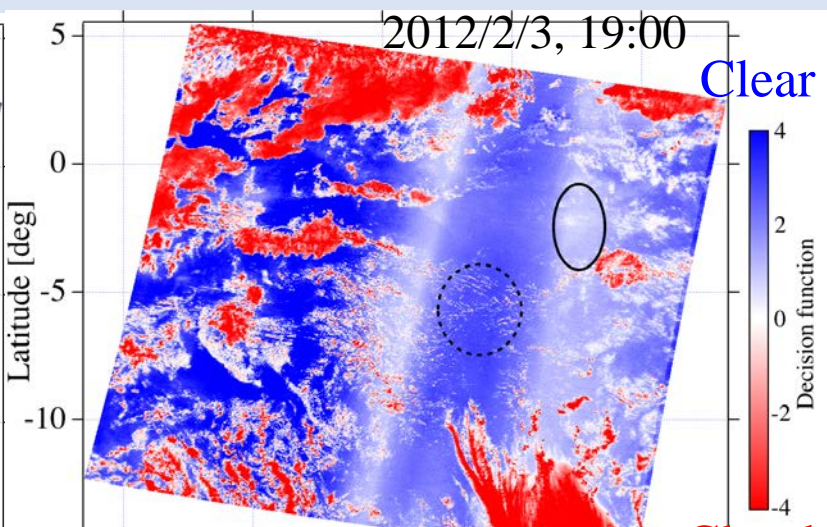
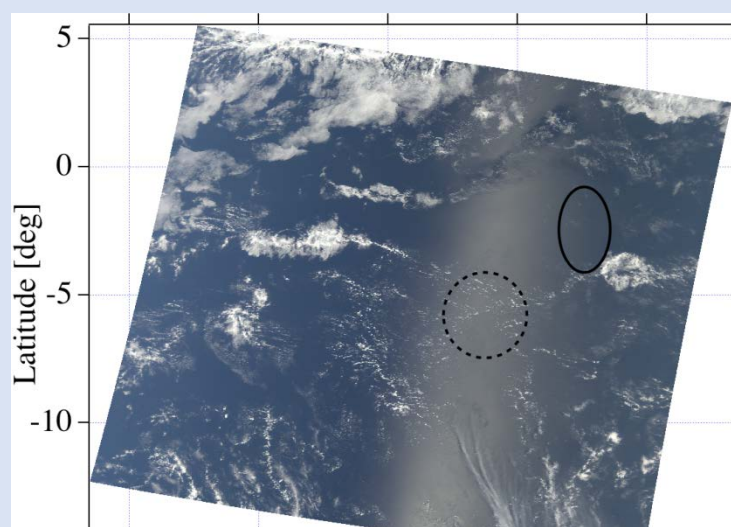
3. Applicability of machine-learning

3-5. Example: Cloud mask

Desert
by MODIS



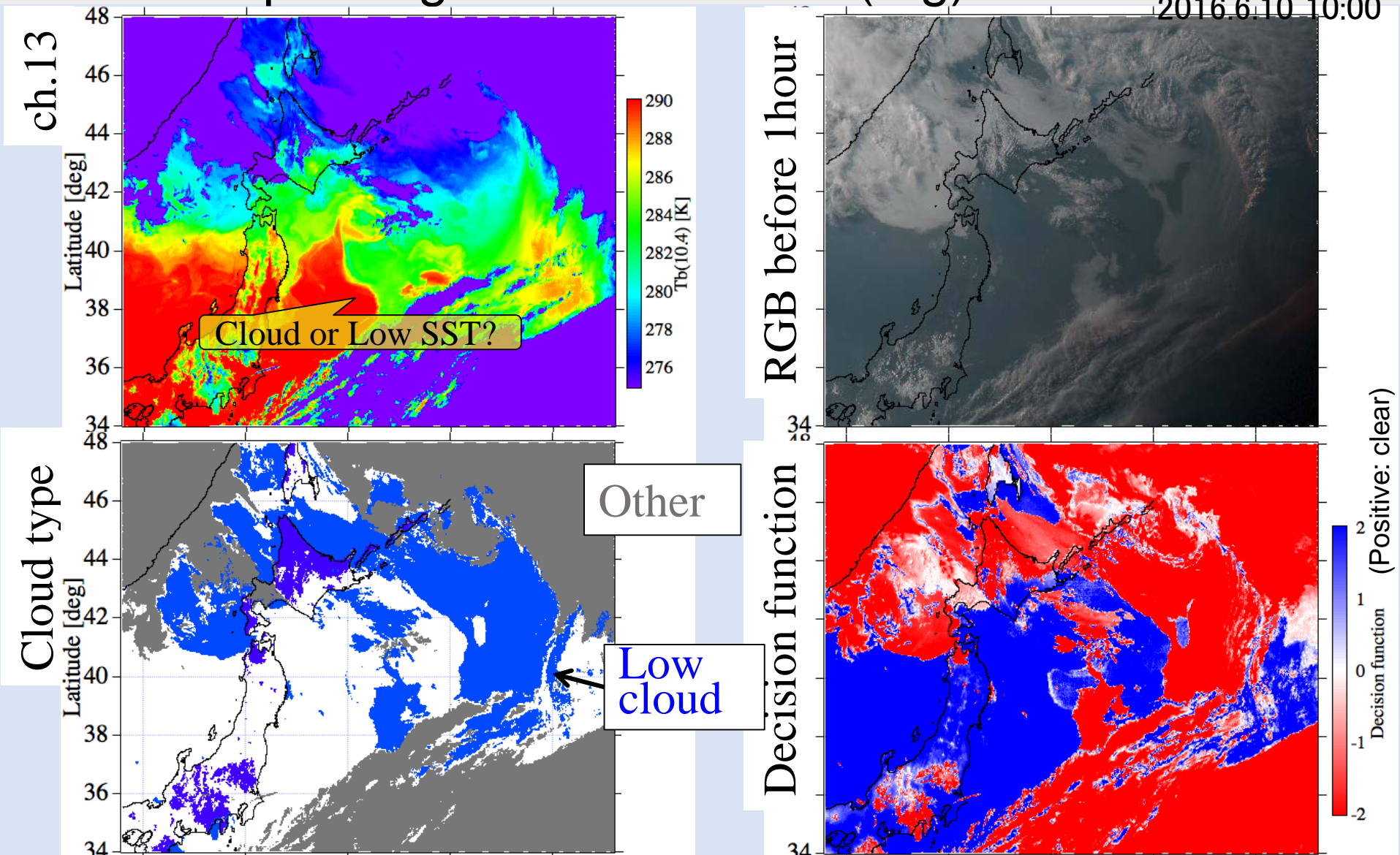
Ocean
by MODIS



The decision function: appropriate for a measure of likelihood

3. Applicability of machine-learning

3-6. Example: Nighttime low cloud (fog) detection



SVM using all IR bands of AHI: reasonable discrimination

4. Conclusions

- AHI cloud product: the algorithm for cloud top height retrieval has been improved.
 - Reduce under estimation in the previous version
- A way of incorporating machine-learning techniques into cloud (type) discrimination
 - To overcome the own difficulties
 - SVM: suitable and applicable
 - ✓ How about other techniques (e.g., Neural Networks)?

appendix

Fundamental Cloud Product: Cloud Mask

- ✓ Threshold tests for observed reflectance and brightness temperature(TBB)
- ✓ Referring to the NWC-SAF and GOES-R/ABI ATBDs
- ✓ Each threshold depends on the clear-sky reflectance/TBB

Reflectance:

- (Land) MODIS BRDF / Albedo product (MOD43)
- (Sea) Cox and Munk, 1954
- (Ice) Aoki et al., 1999, 2000(JGR)

TBB:

- RTTOV calculation on the cloud free condition

Tests	Primary parameters
Snow/sea ice detection	R1.6
Top temperature tests	T10.4
Top reflectance tests	R0.64, T3.9-T10.4
Top emissivity tests	T10.4-T8.6, T10.4-T3.9, T12.4-T3.9
Cloud absorption tests	T10.4-T12.4, T8.6-T10.4, T3.9-T10.4
Atmospheric absorption tests	T7.3-T10.4, T12.4-T10.4

- ✓ In addition, spatial/temporal uniformity tests are applied

For further information:

Imai, T., and R. Yoshida, 2016: Algorithm theoretical basis for Himawari-8 Cloud Mask Product. Meteorological Satellite Center Technical Note, 61

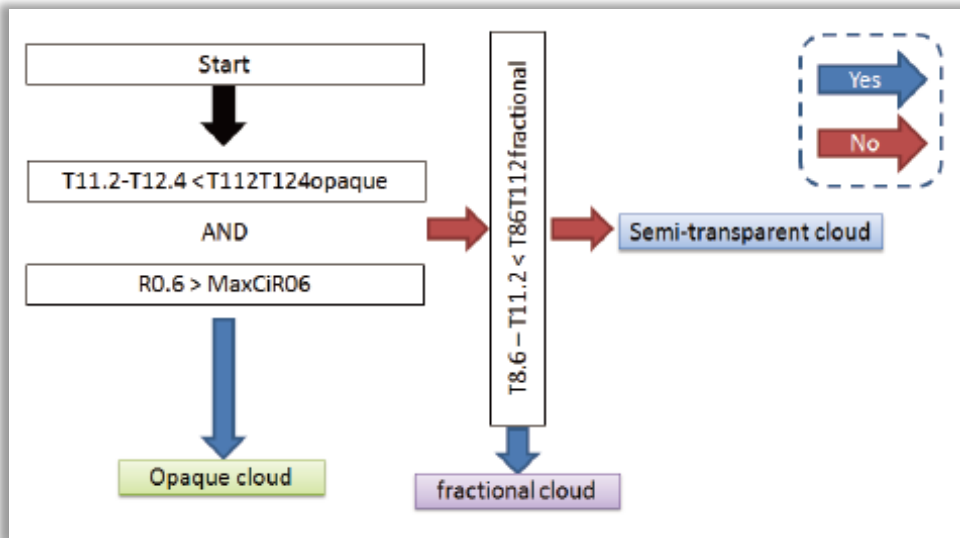
Fundamental Cloud Product: Cloud Type/Phase

✓ Cloud Type

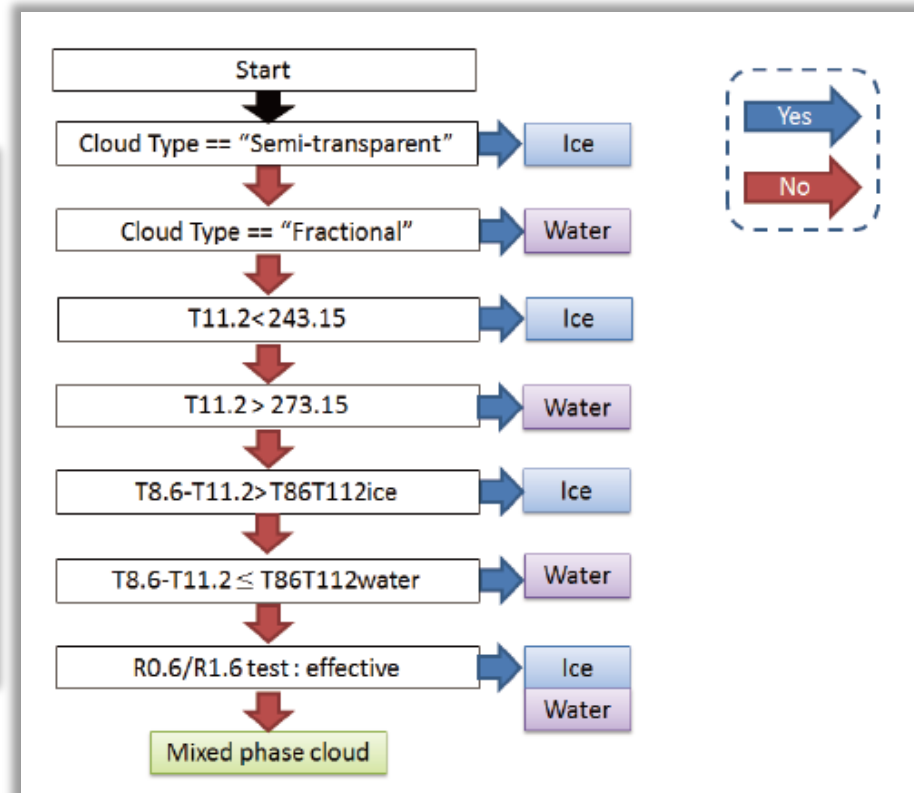
A cloudy pixel is categorized into “opaque”, “semi-transparent” or “fractional”

✓ Cloud Phase

Cloud top phase (Water/Ice/Mixed) is determined based on observed TBB, reflectance and the Cloud Type



Cloud Type determination scheme (daytime)

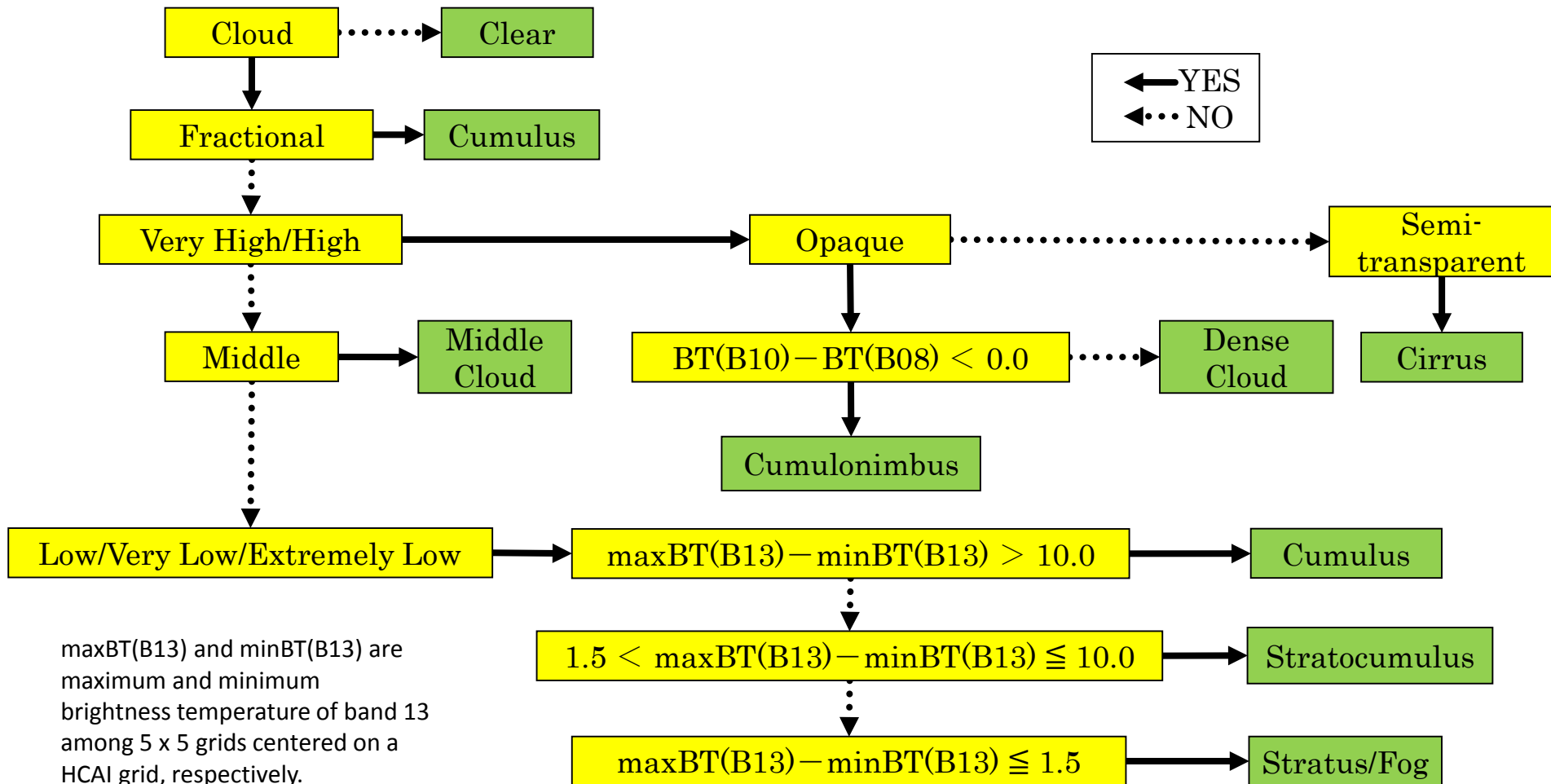


Cloud Phase discrimination scheme (daytime)

For further information:

Mouri et al., 2016: Algorithm Theoretical Basis Document of Cloud Type/Phase Product. Meteorological Satellite Center Technical Note, 61

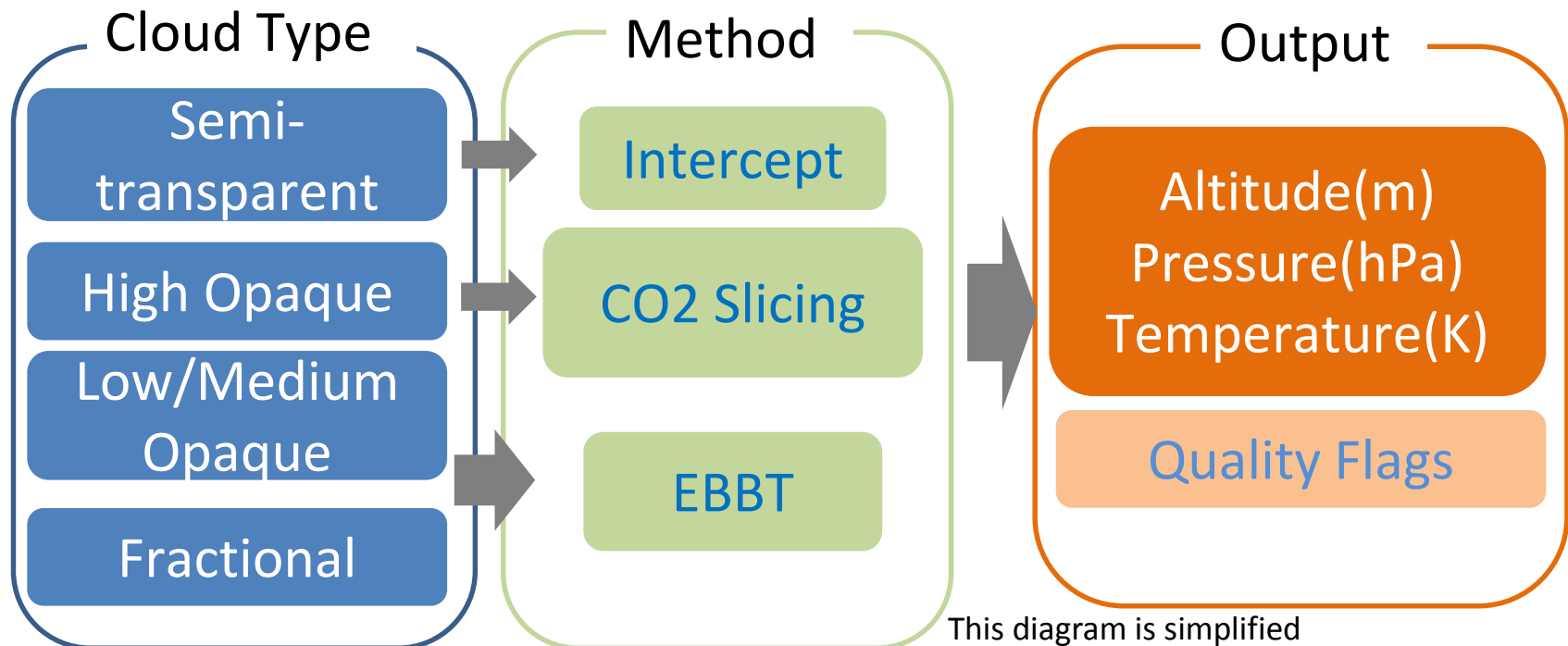
HCAI Cloud Type determination



$\max BT(B13)$ and $\min BT(B13)$ are maximum and minimum brightness temperature of band 13 among 5 x 5 grids centered on a HCAI grid, respectively.

Fundamental Cloud Product: Cloud Top Height

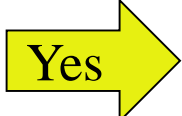
- ✓ Combining three conventional methods
 - CO2 Slicing method (Menzel et al., 1982)
 - IRW/H2O Intercept Method (Schmetz et al., 1993)
 - Equivalent Black Body Temperature (EBBT) Method
- ✓ One method selected based on the cloud type



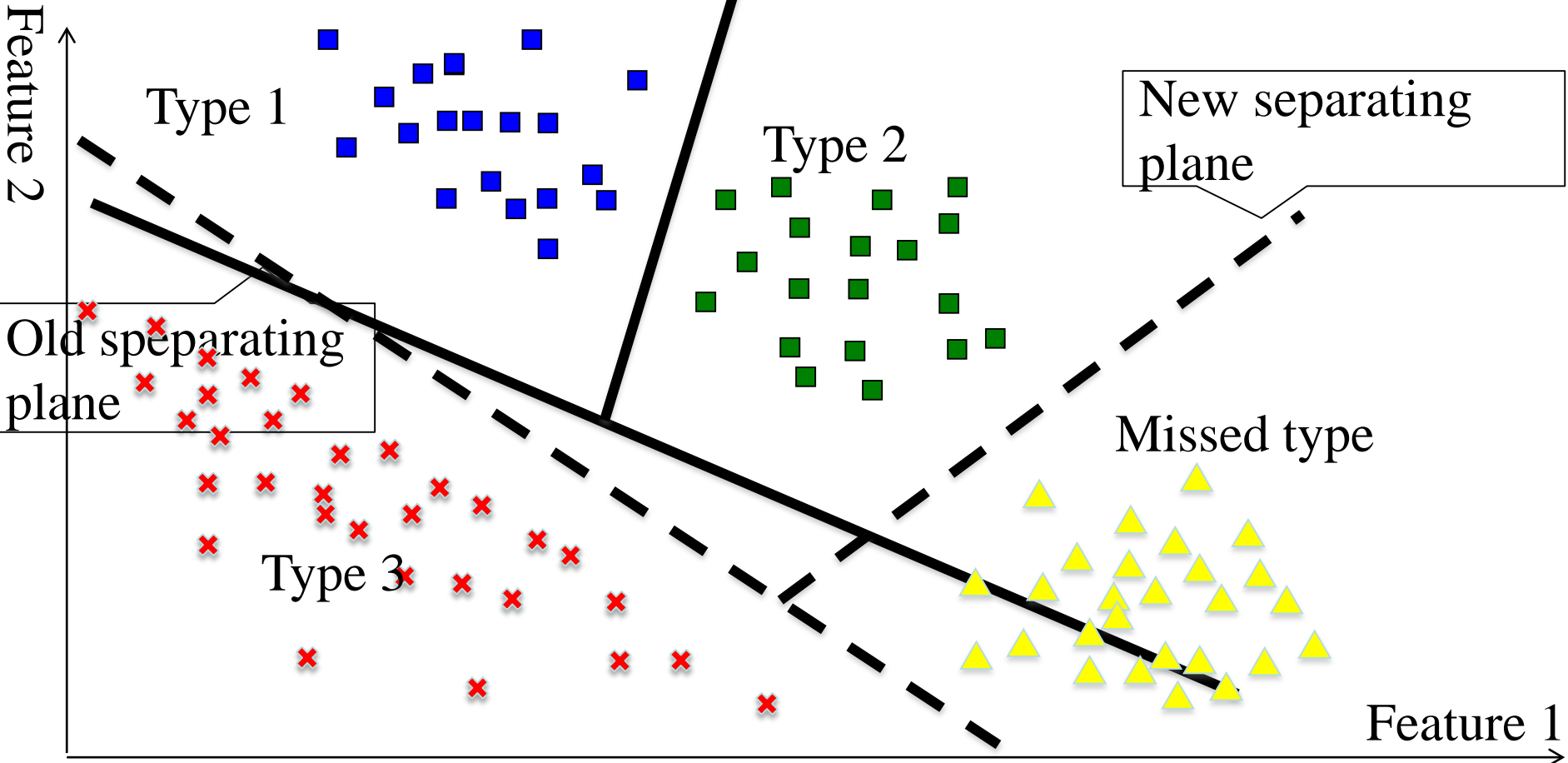
2. Adjustment by adding training dataset

If a type of surface or cloud is usually incorrectly discriminated...

The type is separated in the feature space?



Possible to re-learning with adding the training data



Feature 2

Type 1

Type 2

Old separating plane

New separating plane

Type 3

Missed type

Feature 1

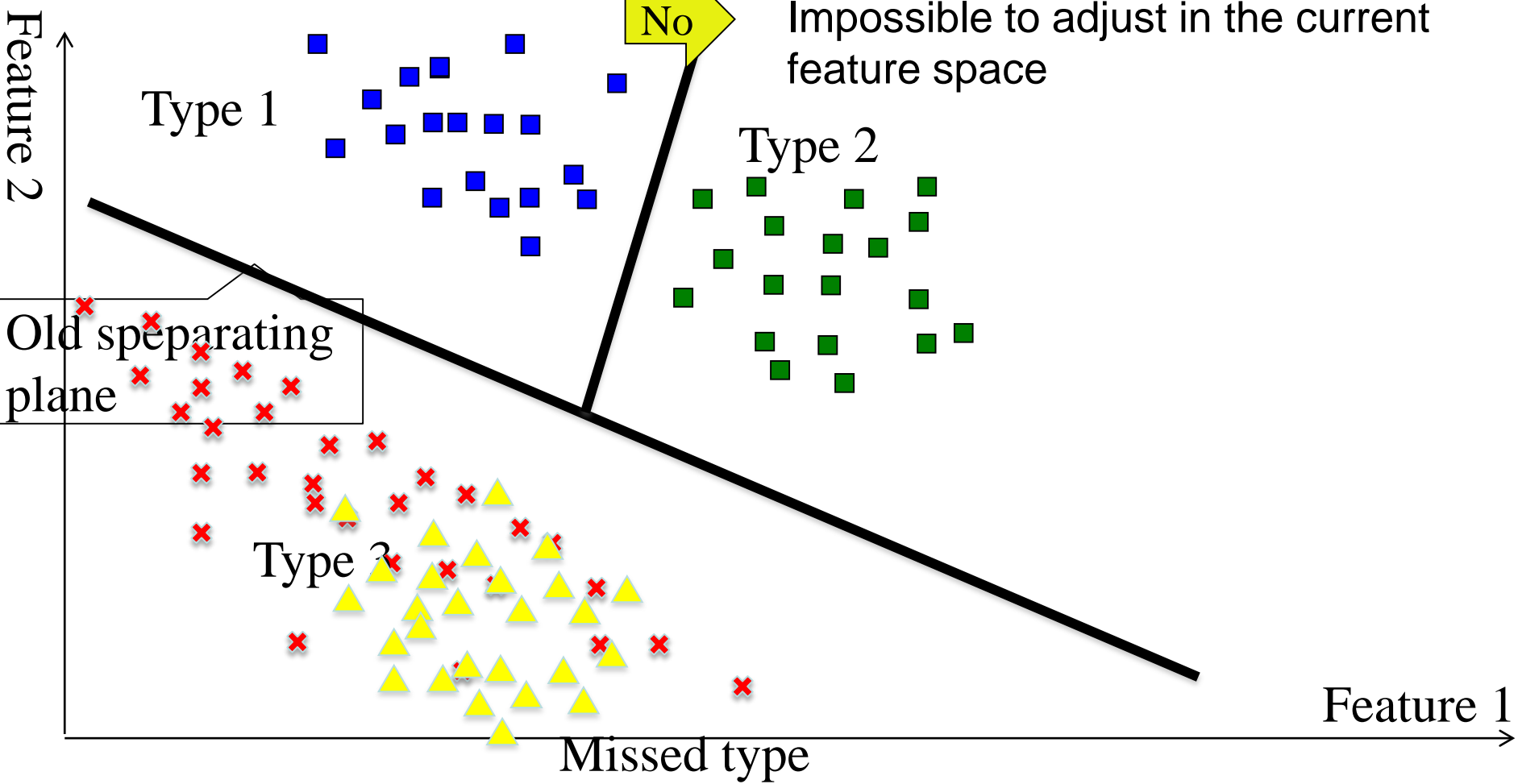
2. Adjustment by adding training dataset

If a type of surface or cloud is usually incorrectly discriminated...

The type is separated in the feature space?

Yes → Possible to re-learning with adding the training data

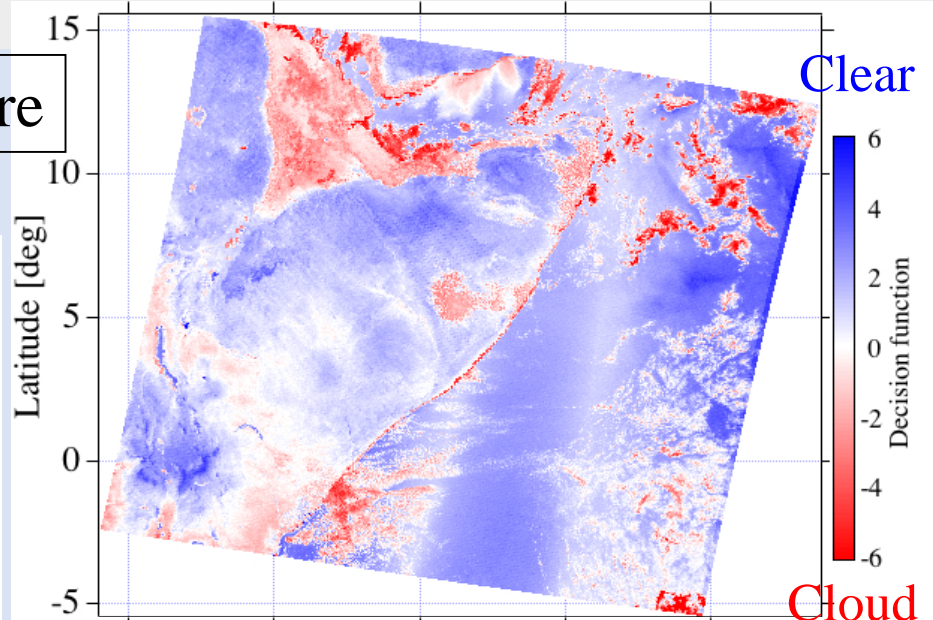
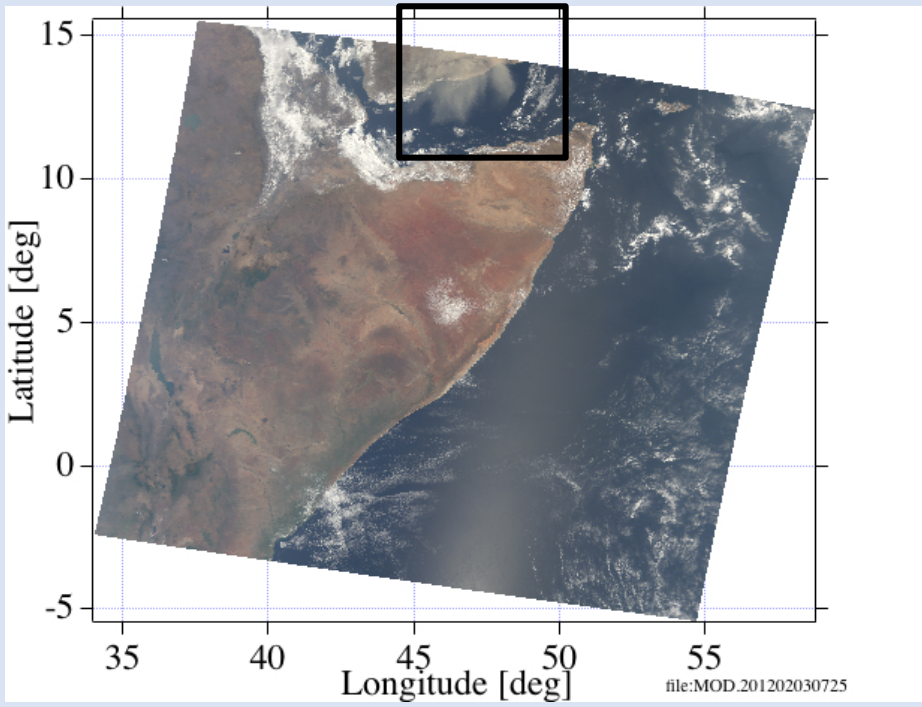
No → Impossible to adjust in the current feature space



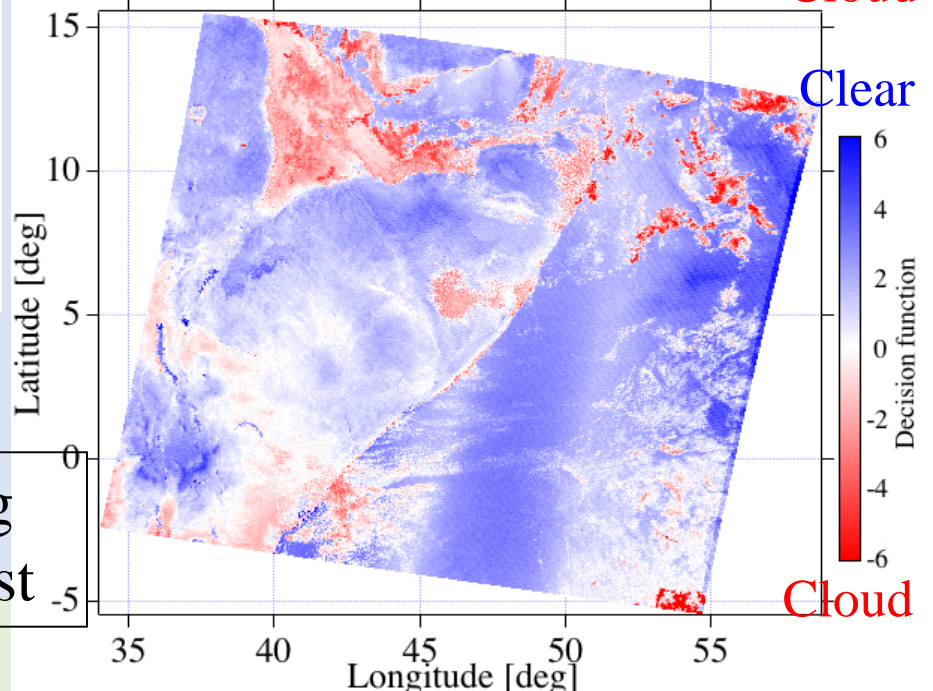
3. Adjustment by adding training dataset

MODIS, dust

Before

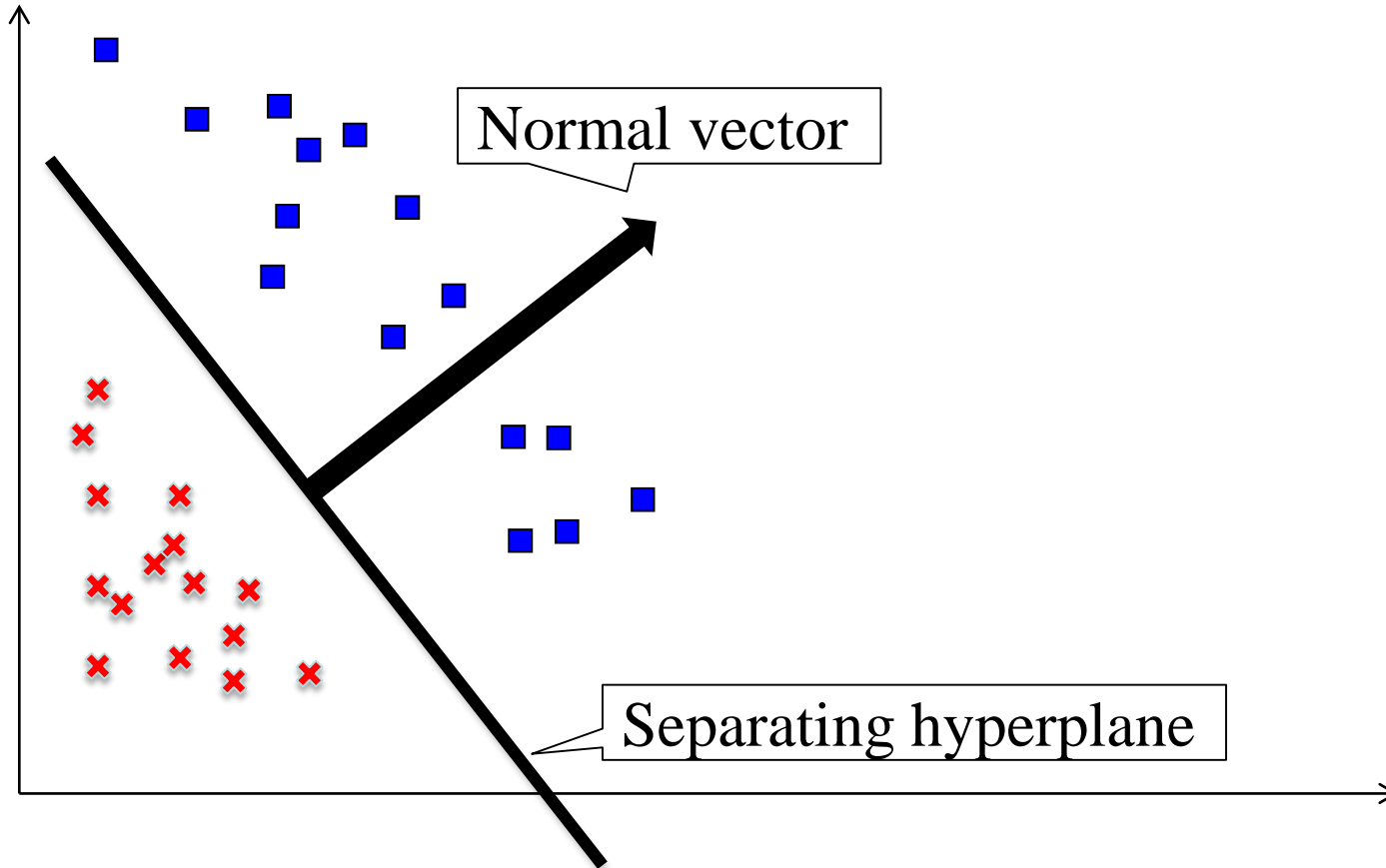


Re-learning adding training data of dust



5. Effectivity of features

5-1. index; length of the projection of the normal vector



The length of the projection of the normal vector means the contribution of the feature to the classification

5. Effectivity of features

5-1. Feature selection

Over water, MODIS

